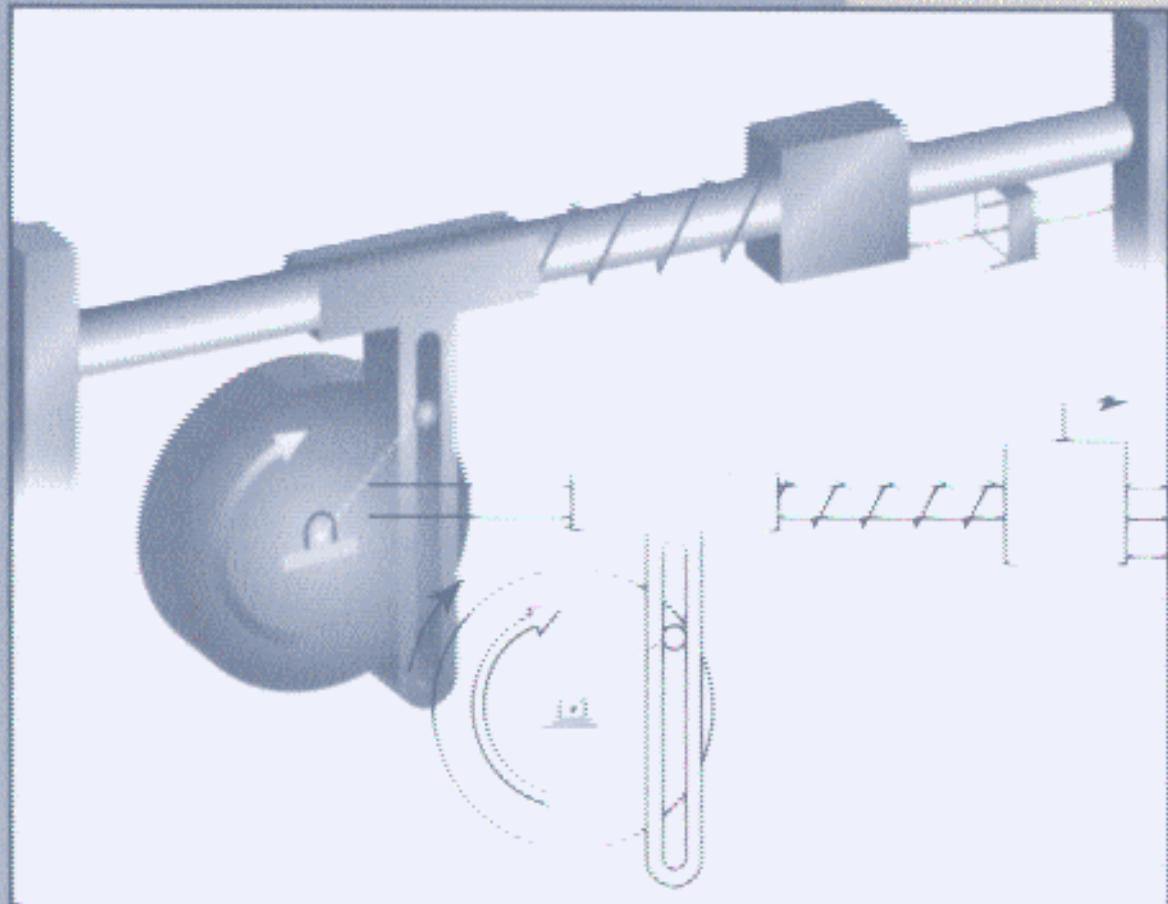


Mechanical and Structural Vibrations

Theory and
Applications



Jerry H. Ginsberg

CHAPTER 1 EQUATIONS OF MOTION FOR DISCRETE SYSTEMS 1

1.1	The Study of Vibrations: An Overview	1
1.2	System Elements	3
1.3	Generalized Coordinates	8
1.4	Newton-Euler Motion Equations	12
1.5	Power Balance Method for Time-Invariant Systems	19
1.5.1	Power Balance Law	20
1.5.2	Linearized Energy and Power	21
1.5.3	Linearized Equations of Motion	24
1.5.4	Implementation	27
References and Selected Readings		54
Exercises		54

CHAPTER 2 TRANSIENT RESPONSE OF ONE-DEGREE-OF-FREEDOM SYSTEM 64

2.1	Harmonic Functions	64
2.1.1	Basic Properties	64
2.1.2	Complex Variable Representation	67
2.1.3	Algebraic Operations	69
2.2	Free Vibration	74
2.2.1	Undamped Systems	76
2.2.2	Underdamped Systems	79
2.2.3	Overdamped Systems	88
2.2.4	Critically Damped Systems	90
2.2.5	Coulomb Friction	94
2.3	Transient Response to Basic Excitations	98
2.3.1	Method of Undetermined Coefficients	98
3.3.2	Superposition and Time Delay	100
3.3.3	Pulse Excitation	104
3.3.4	Step and Impulse Responses	108
3.3.5	Shock Spectra	110
References and Selected Readings		112
Exercises		112

CHAPTER 3 STEADY-STATE RESPONSE TO HARMONIC EXCITATION 121

3.1	Complex Frequency Response	121
3.2	Power Dissipation	130

3.2.1	Quality Factor of Resonance	131
3.2.2	Structural Damping	135
3.3	Resonant Response	139
3.4	Rotating Imbalance	143
3.4.1	Basic Model	143
3.4.2	Frequency Response	148
3.5	Whirling of Shafts	152
3.6	Force Transmission	154
3.7	Periodic Excitations	155
3.7.1	Complex Fourier Series	155
3.7.2	The Discrete Fourier Transform	159
3.7.3	The Inverse Discrete Fourier Transform	162
3.7.4	Explanation and Implementation of the FFT Algorithm	164
3.7.5	Periodic Response Using FFTs	168
3.7.6	Accelerometers and Seismometers	175
3.8	Transient Response Revisited	181
3.8.1	Convolution Integral	181
3.8.2	FFTs for Transient Response	184
References and Selected Readings		206
Exercises		206
<hr/> CHAPTER 4 MODAL ANALYSIS OF MULTI-DEGREE-OF-FREEDOM SYSTEMS 219 <hr/>		
4.1	Background	219
4.2	Eigenvalue Problem—Undamped Systems	223
4.2.1	Natural Frequencies and Modes	223
4.2.2	Orthogonality and Normalization	230
4.2.3	Computerized Implementations	235
4.2.4	Flexibility Coefficients	241
4.2.5	Repeated Natural Frequencies	245
4.2.6	Rigid Body Modes	252
4.3	Modal Equations	256
4.3.1	Coordinate Transformations	256
4.3.2	Modal Coordinates	257
4.3.3	Modal Coordinate Description of Mechanical Energy and Power	260
4.3.4	Free Vibration Response	261
4.3.5	Forced Response	268
4.3.6	Modal Damping	269

4.3.7	Harmonic Steady-State Response 274
-------	---------------------------------------

References and Selected Readings	283
----------------------------------	-----

Exercises	283
-----------	-----

CHAPTER 5 HARMONIC EXCITATION OF MULTI-DEGREE-OF-FREEDOM SYSTEMS 294

5.1	Frequency Domain Transfer Function 294
-----	--

5.2	Structural Damping and Modal Analysis 297
-----	--

5.3	Vibration Absorber 301
-----	------------------------

5.4	FFT Techniques 306
-----	--------------------

5.4.1	Analysis of Transient Response 306
-------	------------------------------------

5.4.2	Experimental Modal Analysis 313
-------	---------------------------------

References and Selected Readings	317
----------------------------------	-----

Exercises	317
-----------	-----

CHAPTER 6 VIBRATION OF ELASTIC BARS: THE RITZ METHOD AND THE RAYLEIGH RATIO 324

6.1	Equations of Motion 325
-----	-------------------------

6.1.1	Axial Displacement 326
-------	------------------------

6.1.2	Torsion of Circular Bars 338
-------	------------------------------

6.1.3	Flexural Displacement 341
-------	---------------------------

6.1.4	Implementation and Solution 352
-------	---------------------------------

6.2	Eigensolutions 357
-----	--------------------

6.3	Modal Analysis 367
-----	--------------------

6.3.1	Orthogonality of the Mode Functions 367
-------	--

6.3.2	Modal Response 371
-------	--------------------

6.3.3	Initial Conditions: The Expansion Theorem 373
-------	--

6.3.4	Free Vibration 375
-------	--------------------

6.3.5	Impulse Response 376
-------	----------------------

6.3.6	Harmonic Steady-State Response 376
-------	---------------------------------------

6.4	Rayleigh Ratio and Convergence Properties 381
-----	--

6.5	Time-Dependent Boundary Conditions 394
-----	---

6.6	Ritz Method for Discrete Systems 403
-----	--------------------------------------

References and Selected Readings	406
----------------------------------	-----

Exercises	406
-----------	-----

CHAPTER 7 FIELD DESCRIPTIONS FOR VIBRATING BARS 414

7.1	Derivation of Motion Equations 415
-----	------------------------------------

7.1.1	Field Equations 415
-------	---------------------

7.1.2	Boundary Conditions 420
-------	-------------------------

7.2	Eigensolutions for Extension and
-----	----------------------------------

Torsion 424

7.3	Eigensolutions for Flexure 432
-----	--------------------------------

7.4	Wave Interpretation of Modes and High-Frequency Asymptotics 441
-----	--

7.5	Symmetry and Mode Functions 447
-----	---------------------------------

7.6	Orthogonality 450
-----	-------------------

7.7	Modal Analysis of Response 458
-----	--------------------------------

7.7.1	Modal Equations 458
-------	---------------------

7.7.2	Steady-State and Transient Response 458
-------	--

7.8	Time-Dependent Boundary Conditions 469
-----	---

7.8.1	Mindlin-Goodman Decomposition 469
-------	--------------------------------------

7.8.2	Harmonic Boundary Excitation Wave Solution 474
-------	---

7.9	Timoshenko Beam Theory 482
-----	----------------------------

7.9.1	Field Equations 482
-------	---------------------

7.9.2	Wave Solutions 487
-------	--------------------

7.9.3	Modal Analysis 490
-------	--------------------

References and Selected Readings	498
----------------------------------	-----

Exercises	498
-----------	-----

CHAPTER 8 THE FINITE ELEMENT METHOD 506

8.1	Interpolating Functions 506
-----	-----------------------------

8.2	Elemental Matrices 509
-----	------------------------

8.3	Conversion to Global Coordinates 513
-----	--------------------------------------

8.4	Assembly of the Elements 517
-----	------------------------------

8.5	Reaction Forces and Constraint Conditions 523
-----	--

References and Selected Readings	528
----------------------------------	-----

Exercises	528
-----------	-----

CHAPTER 9 SUBSTRUCTURING CONCEPTS 532

9.1	Method of Lagrange Multipliers 532
-----	------------------------------------

9.1.1	Constraint Equations and Reactions 532
-------	---

9.1.2	Synthesis of the Equations of Motion 539
-------	---

9.1.3	Solution Methods 542
-------	----------------------

9.2	Component Mode Synthesis 552
-----	------------------------------

9.2.1	Relaxation of Constraints 552
-------	-------------------------------

9.2.2	Component Properties 558
-------	--------------------------

References and Selected Readings	562
----------------------------------	-----

Exercises	562
-----------	-----

CHAPTER 10 DAMPED MODAL ANALYSIS: THE STATE SPACE 565

10.1	State-Space Equations 565
------	---------------------------

10.2	Eigenvalue Problem 567
------	------------------------

10.3	Relation to Previous Developments	589
10.4	Orthogonality	575
10.5	Modal Coordinates	580
10.5.1	Free Vibration	581
10.5.2	Impulsive Forces	582
10.5.3	Steady-State Harmonic Vibration	583
10.5.4	Rigid Body Motion	584
10.5.5	Closure	585
References and Selected Readings		591
Exercises		591

CHAPTER 11 MODAL ANALYSIS OF GYROSCOPIC SYSTEMS 595

11.1	General Linearized Equations of Motion	595
11.2	Right and Left Eigenvalue Problems	606
11.3	Dynamic Stability	613
11.4	Bi-orthogonality and Modal Equations of Motion	619
11.5	Moving Continuous Systems	627
References and Selected Readings		641
Exercises		642

CHAPTER 12 INTRODUCTION TO ROTORDYNAMICS 647

12.1	Elements of a Rotordynamic Model	647
12.2	Effects of Internal and External Damping	650
12.3	Flexible Orthotropic Bearings	658
12.4	Gyroscopic Effects	661
12.5	Flexible Orthotropic Shafts	668
References and Selected Readings		674
Exercises		674

APPENDIX A LAGRANGE'S EQUATIONS 677

APPENDIX B TRANSIENT RESPONSES FOR UNDERDAMPED ONE-DEGREE-OF-FREEDOM SYSTEMS 685

APPENDIX C DEFORMATION MODES FOR UNIFORM BARS 686

INDEX 687
