Chitta Baral

Knowledge
Representation,
Reasoning and
Declarative Problem
Solving

CAMBRIDGE

Contents

	Prefa	ice I	oage ix
1	Declarative programming in AnsProlog*: introduction and prelimina		es 1
	1.1	Motivation: Why AnsProlog*?	3
	1.2	Answer set frameworks and programs	8
	1.3	Semantics of AnsProlog* programs	16
	1.4	Database queries and AnsProlog* functions	40
	1.5	Notes and references	44
2	Simple modules for declarative programming with answer sets		46
	2.1	Declarative problem solving modules	47
	2.2	Knowledge representation and reasoning modules	73
	2.3	Notes and references	81
3	Princ	iples and properties of declarative programming with answer sets	83
	3.1	Basic notions and basic properties	84
	3.2	Some AnsProlog* sub-classes and their basic properties	93
	3.3	Restricted monotonicity and signed AnsProlog* programs	108
	3.4	Analyzing AnsProlog* programs using 'splitting'	113
	3.5	Language independence and language tolerance	120
	3.6	Interpolating an AnsProlog program	126
	3.7	Building and refining programs from components: functional	
		specifications and realization theorems	137
	3.8	Filter-abducible AnsProlog ^{¬, Or} programs	144
	3.9	Equivalence of programs and semantics preserving	
		transformations	154
	3.10	Notes and references	168
4	Declarative problem solving and reasoning in AnsProlog*		170
	4.1	Three well-known problem solving tasks	170
	4.2	Constraint satisfaction problems (CSPs)	183

vi Contents

	4.3	Dynamic constraint satisfaction problems (DCSPs)	186		
	4.4	Combinatorial graph problems	188		
	4.5	Prioritized defaults and inheritance hierarchies	192		
	4.6	Notes and references	197		
5	Reasoning about actions and planning in AnsProlog*				
	5.1	Reasoning in the action description language \mathcal{A}	199		
	5.2	Reasoning about actions and plan verification in richer domains	229		
	5.3	Answer set planning examples in extensions of \mathcal{A} and STRIPS	244		
	5.4	Approximate planning when initial state is incomplete	261		
	5.5	Planning with procedural constraints	262		
	5.6	Explaining observations through action occurrences and			
		application to diagnosis	269		
	5.7	Case study: Planning and plan correctness in a space shuttle			
		reaction control system	274		
	5.8	Notes and references	277		
6	Complexity, expressiveness, and other properties of AnsProlog*				
	pro	ograms	278		
	6.1	Complexity and expressiveness	278		
	6.2	Complexity of AnsDatalog* sub-classes	288		
	6.3	Expressiveness of AnsDatalog* sub-classes	301		
	6.4	Complexity and expressiveness of AnsProlog* sub-classes	304		
	6.5	Compact representation and compilability of AnsProlog	311		
	6.6	Relationship with other knowledge representation formalisms	313		
	6.7	Notes and references	341		
7	Answer set computing algorithms				
	7.1	Branch and bound with WFS: wfs-bb	346		
	7.2	The assume-and-reduce algorithm of SLG	358		
	7.3	The smodels algorithm	363		
	7.4	The dlv algorithm	372		
	7.5	Notes and references	379		
8	Query answering and answer set computing systems		382		
	8.1	Smodels	382		
	8.2	The dlv system	403		
	8.3	Applications of answer set computing systems	412		
	8.4	Pure PROLOG	440		
	8.5	Notes and references	456		
9	Furth	ner extensions of and alternatives to AnsProlog*	458		
	9.1	AnsProlognot or :: allowing not in the head	458		
	9.2	AnsProlog(\mathbf{not} . or , \neg , \bot)*: allowing nested expressions	461		
	0.3	AnsProlog - Or.K.M. allowing knowledge and belief operators	466		

	Contents	v
9.4	Abductive reasoning with AnsProlog: AnsProlog ^{abd}	476
9.5	Domain closure and the universal query problem	47
9.6	AnsProlog _{set} : adding set constructs to AnsProlog	47:
9.7	AnsProlog-< programs: AnsProlog programs with ordering	47
9.8	Well-founded semantics of programs with AnsProlog syntax	482
9.9	Well-founded semantics of programs with AnsProlog syntax	490
9.10	Notes and references	492
Appendix .	A: Ordinals, lattices, and fixpoint theory	494
Appendix B: Turing machines		
Bibliograp	hy	498
Index of notation		
Index of terms		