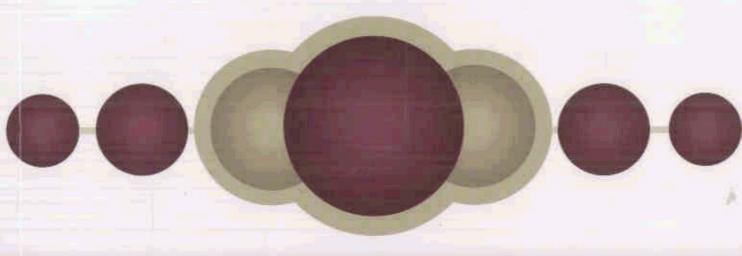
# CONTROL SYSTEMS ENGINEERING



FIFTH EDITION

Norman S. Nise

International Student Version

## CONTENTS

PRE	FACE,	хi
PNL	/*\\~ -/	ΛI

1.	<b>BASIC</b>	CONT	RQL	SYS1	ΓΕΙ <mark>Μ</mark>
	CONC	EPTS.	1		

- 1.1 Introduction, 2
- 1.2 A History of Control Systems, 4
- 1.3 System Configurations, 8
- 1.4 Analysis and Design Objectives, 10 Introduction to a Case Study, 12
- 1.5 The Design Process, 15
- 1.6 Computer-Aided Design, 20
- 1.7 The Control Systems Engineer, 22
  Summary, 23
  Review Questions, 23
  Problems, 24
  Progressive Analysis and Design
  Problems, 28
  Bibliography, 29

# 2. TRANSFER FUNCTIONS OF PHYSICAL SYSTEMS, 31

- 2.1 Introduction, 32
- 2.2 Laplace Transform Review, 32
- 2.3 The Transfer Function, 42
- 2.4 Electrical Network Transfer Functions, 45
- 2.5 Translational Mechanical System Transfer Functions, 59
- 2.6 Rotational Mechanical System Transfer Functions, 66
- 2.7 Transfer Functions for Systems with Gears, 71

- 2.8 Electromechanical System Transfer Functions, 75
- 2.9 Electric Circuit Analogs, 81
- 2.10 Nonlinearities, 84
- 2.11 Linearization, 85
  Case Studies, 90

Summary, 93

Review Questions, 93 Problems, 94

**Progressive Analysis and Design** 

Problems, 105

Cyber Exploration Laboratory, 106

Bibliography, 109

# 3. STATE EQUATIONS FOR PHYSICAL SYSTEMS, 111

- 3.1 Introduction, 112
- 3.2 Some Observations, 112
- 3.3 The General State-Space Representation, 116
- 3.4 Applying the State-Space Representation, 118
- 3.5 Converting a Transfer Function to State Space, 126
- 3.6 Converting from State Space to a Transfer Function, 133
- 3.7 Linearization, 135
  Case Studies, 138
  Summary, 142
  Review Ouestions, 143

Problems. 144

Progressive Analysis and Design Problems, 149 Cyber Exploration Laboratory, 150 Bibliography, 151

### 4. TRANSIENT RESPONSE, 153

- 4.1 Introduction, 154
- 4.2 Poles, Zeros, and System Response, 154
- 4.3 First-Order Systems, 157
- 4.4 Second-Order Systems: Introduction, 160
- 4.5 The General Second-Order System, 165
- 4.6 Underdamped Second-Order Systems, 168
- 4.7 System Response with Additional Poles, 177
- 4.8 System Response with Zeros, 181
- 4.9 Effects of Nonlinearities upon Time Response, 187
- 4.10 Laplace Transform Solution of State Equations, 190
- 4.11 Time Domain Solution of State
  Equations, 193
  Case Studies, 198
  Summary, 203
  Review Questions, 205
  Problems, 206
  Design Problems, 215
  Progressive Analysis and Design
  Problems, 217
  Cyber Exploration Laboratory, 218
  Bibliography, 221

### 5. EQUIVALENT SYSTEMS, 223

- 5.1 Introduction, 224
- 5.2 Block Diagrams, 224
- 5.3 Analysis and Design of Feedback Systems, 233
- 5.4 Signal-Flow Graphs, 236
- 5.5 Mason's Rule. 239
- 5.6 Signal-Flow Graphs of State Equations, 242
- 5.7 Alternative Representations in State Space, 244
- 5.8 Similarity Transformations, 254

Case Studies, 262
Summary, 268
Review Questions, 269
Problems, 270
Design Problems, 283
Progressive Analysis and Design
Problems, 284
Cyber Exploration Laboratory, 285
Bibliography, 286

# 6. TRANSIENT RESPONSE STABILITY, 287

- 6.1 Introduction, 288
- 6.2 Routh-Hurwitz Criterion, 291
- 6.3 Routh-Hurwitz Criterion: Special Cases. 294
- 6.4 Routh-Hurwitz Criterion: Additional Examples, 300
- 6.5 Stability in State Space, 306
  Case Studies, 309
  Summary, 311
  Review Questions, 311
  Problems, 312
  Design Problems, 317
  Progressive Analysis and Design
  Problems, 319
  Cyber Exploration Laboratory, 320
  Bibliography, 321

### 7. FORCED RESPONSE ERRORS, 323

- 7.1 Introduction, 324
- 7.2 Steady-State Error for Unity Feedback Systems, 327
- 7.3 Static Error Constants and System Type, 333
- 7.4 Steady-State Error Specifications, 337
- 7.5 Steady-State Error for Disturbances, 339
- 7.6 Steady-State Error for Nonunity Feedback
  Systems, 341
- 7.7 Sensitivity, 345
- 7.8 Steady-State Error for Systems in State Space, 348
  Case Studies. 352

Contents vii

Summary, 355
Review Questions, 356
Problems, 357
Design Problems, 365
Progressive Analysis and Design
Problems, 367
Cyber Exploration Laboratory, 368
Bibliography, 369

### 8. A GRAPHICAL TOOL, 370

- 8.1 Introduction, 371
- 8.2 Defining the Root Locus, 375
- 8.3 Properties of the Root Locus, 378
- 8.4 Sketching the Root Locus, 381
- 8.5 Refining the Sketch, 386
- 8.6 An Example, 395
- 8.7 Transient Response Design via Gain Adjustment, 399
- 8.8 Generalized Root Locus, 404
- 8.9 Root Locus for Positive-Feedback Systems, 405
- 8.10 Pole Sensitivity, 408
  Case Studies, 410
  Summary, 416
  Review Questions, 416
  Problems, 417
  Design Problems, 427
  Progressive Analysis and Design
  Problems, 430
  Cyber Exploration Laboratory, 432
  Bibliography, 433

### DESIGN USING THE GRAPHICAL TOOL, 435

- 9.1 Introduction, 436
- 9.2 Improving Steady-State Error via Cascade Compensation, 439
- 9.3 Improving Transient Response via Cascade Compensation, 449
- 9.4 Improving Steady-State Error and Transient Response, 463
- 9.5 Feedback Compensation, 476
- 9.6 Physical Realization of Compensation, 485

Case Studies, 490
Summary, 495
Review Questions, 496
Problems, 497
Design Problems, 503
Progressive Analysis and Design
Problems, 510
Cyber Exploration Laboratory, 510
Bibliography, 512

### 10. SINUSOIDAL TOOLS, 513

- 10.1 Introduction, 514
- 10.2 Asymptotic Approximations: Bode Plots, 520
- 10.3 Introduction to the Nyquist Criterion, 539
- 10.4 Sketching the Nyquist Diagram, 544
- 10.5 Stability via the Nyquist Diagram, 549
- 10.6 Gain Margin and Phase Margin via the Nyquist Diagram, 553
- 10.7 Stability, Gain Margin, and Phase Margin via Bode Plots, 556
- 10.8 Relation between Closed-Loop Transient and Closed-Loop Frequency Responses, 559
- 10.9 Relation between Closed- and Open-Loop Frequency Responses, 563
- 10.10 Relation between Closed-Loop Transient and Open-Loop Frequency Responses, 569
- 10.11 Steady-State Error Characteristics from Frequency Response, 573
- 10.12 Systems with Time Delay, 577
- 10.13 Obtaining Transfer Functions
  Experimentally, 581
  Case Study, 585
  Summary, 587
  Review Questions, 589
  Problems, 590
  Progressive Analysis and Design
  Problems, 599

Bibliography, 601

Cyber Exploration Laboratory, 600

# 11. DESIGN USING SINUSOIDAL TOOLS, 602

- 11.1 Introduction, 603
- 11.2 Transient Response via Gain Adjustment, 604
- 11.3 Lag Compensation, 607
- 11.4 Lead Compensation, 612
- 11.5 Lag-Lead Compensation, 618
  Case Studies, 622
  Summary, 625
  Review Questions, 625
  Problems, 626
  Design Problems, 629
  Progressive Analysis and Design
  Problems, 631
  Cyber Exploration Laboratory, 632
  Bibliography, 633

# 12. DESIGN USING STATE EQUATIONS, 635

- 12.1 Introduction, 636
- 12.2 Controller Design, 637
- 12.3 Controllability, 643
- 12.4 Alternative Approaches to Controller Design, 648
- 12.5 Observer Design, 653
- 12.6 Observability, 660
- 12.7 Alternative Approaches to Observer Design, 664
- 12.8 Steady-State Error Design via Integral Control, 671
  Case Study, 674
  Summary, 680
  Review Questions, 681
  Problems, 682
  Design Problems, 686
  Progressive Analysis and Design
  Problems, 689
  Cyber Exploration Laboratory, 689

### 13. DISCRETE CONTROL SYSTEMS, 692

13.1 Introduction, 693

Bibliography, 690

- 13.2 Modeling the Digital Computer, 696
- 13.3 The z-Transform, 699
- 13.4 Transfer Functions, 704
- 13.5 Block Diagram Reduction, 708
- 13.6 Stability, 711
- 13.7 Steady-State Errors, 718
- 13.8 Transient Response on the z-Plane, 722
- 13.9 Gain Design on the z-Plane, 724
- 13.10 Cascade Compensation via the s-Plane, 728
- 13.11 Implementing the Digital Compensator, 731

Case Studies, 734

Summary, 739

Review Questions, 740

Problems, 741

Design Problems, 744

**Progressive Analysis and Design** 

Problems, 746

Cyber Exploration Laboratory, 747

Bibliography, 748

Appendix A List of Symbols, 750

Appendix B MATLAB Tutorial, 754

Appendix C MATLAB's Simulink Tutorial, 807

Glossary, 830

Answers to Selected Problems, 839

Credits, 845

Index, 847

Appendix D MATLAB's GUI Tools Tutorial,
Web site

Appendix E MATLAB's Symbolic Math Toolbox Tutorial, Web site

Appendix F Matrices, Determinants, and Systems of Equations, Web site

- **F.1 Matrix Definitions and Notations**
- F.2 Matrix Operations
- F.3 Matrix and Determinant Identities

iх

F.4 Systems of Equations Bibliography			Appendix K Derivation of Similarity Transformations, Web site		
	Appendix G	Control System Computational Aids, Web site	Appendix L	Root Locus Rules: Derivations, Web site	
G.1 Step Response of a System Represented in State Space G.2 Root Locus and Frequency Response		L.1 Behavior of the Root Locus at Infinity L.2 Derivation of Transition Method for Breakaway and Break-in Points			
	Appendix H	Derivation of a Schematic for a DC Motor, Web site	Solutions to Web site	Skill-Assessment Exercises,	
	Appendix I Derivation of the Time Domain Solution of State		Control Systems Engineering Toolbox, Web site		
		Equations, Web site	Lecture Grap	ohics, Web site	
	Appendix J	Solution of State Equations for $t_o \neq 0$ , Web site	Cyber Explor Web site	ation Laboratory Experiments,	