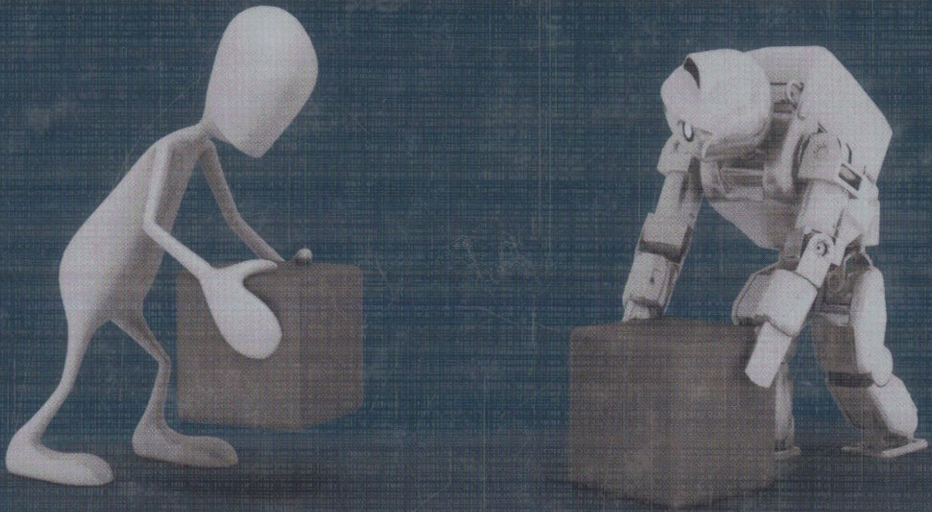
Engineering Sciences   *Micro- and Nanotechnology*

ROBOT PROGRAMMING BY DEMONSTRATION: A PROBABILISTIC APPROACH

Sylvain Calinon



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