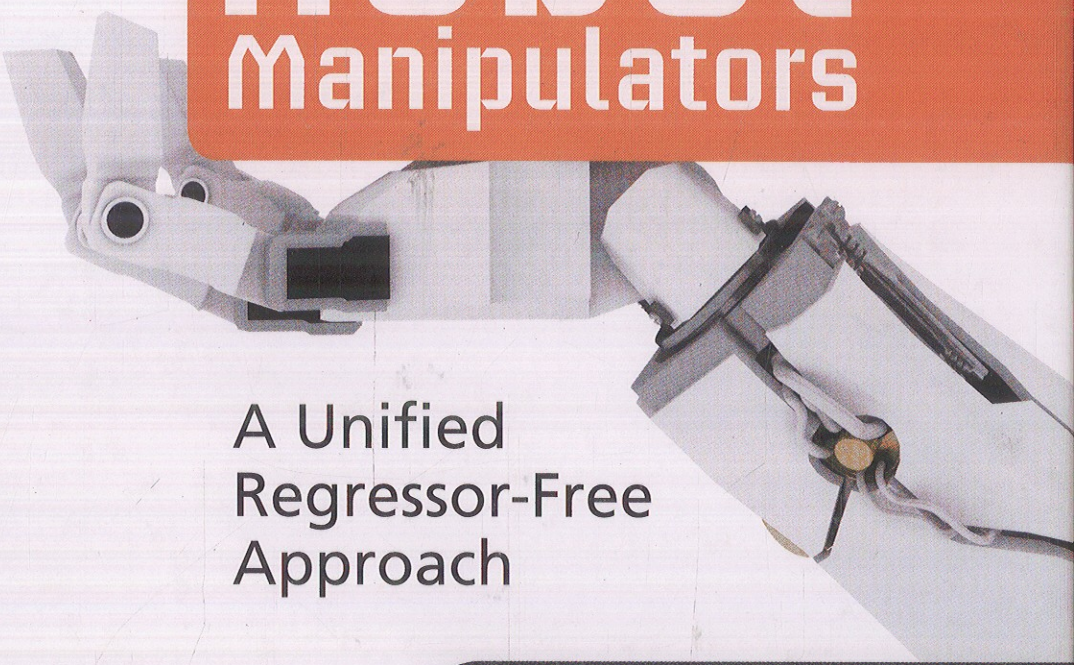
Adaptive Control of Robot Manipulators



A Unified Regressor-Free Approach

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