

Contents

List of Figures	xi
List of Tables	xvii
Preface	xix
About the Editors	xxi
List of Contributors	xxiii
Nomenclature	xxv
1 Introduction	1
<i>Takashi Yamaguchi</i>	
1.1 Concept of High-Speed Precision Motion Control	1
1.2 Hard Disk Drives (HDDs)	4
Bibliography	9
2 System Modeling and Identification	11
<i>Hiroshi Uchida, Takashi Yamaguchi, and Hidehiko Numasato</i>	
2.1 HDD Servo Systems	11
2.1.1 Inside an HDD	12
2.1.2 Generation of Servo Position Signal	13
2.2 TMR Budget Design	16
2.3 Modeling of HDD	22
2.3.1 Introduction	22
2.3.2 Plant Components	22
2.3.3 Modeling of Mechanical Dynamics	24
2.4 Modeling of Disturbances and PES	32
2.4.1 Disturbances and PES	32
2.4.2 Decomposition of Steady-State PES	34
2.4.2.1 RRO and NRRO	34
2.4.2.2 Frequency Spectrum of NRRO	36
2.4.2.3 Decomposition of NRRO	37
2.4.3 Decomposition of Transient Response	40
Bibliography	46

3 Basic Approach to High-Speed Precision Motion Control	49
<i>Atsushi Okuyama, Takashi Yamaguchi, Takeyori Hara, and Mitsuo Hirata</i>	
3.1 Introduction to Mode Switching Control (MSC)	50
3.2 Track-Seeking: Fast Access Servo Control	51
3.2.1 Two-Degrees-of-Freedom (TDOF) Control	51
3.2.1.1 Advantages of TDOF Control	51
3.2.1.2 Structure of TDOF Control	53
3.2.1.3 Zero-Phase Error Tracking Control (ZPETC) .	53
3.2.1.4 Reference Trajectory	55
3.2.2 Access Servo Control Considering Saturation	58
3.2.2.1 Basic Structure of Access Servo Control . . .	59
3.2.2.2 Reference Velocity Trajectory	61
3.2.2.3 Proximate Time-Optimal Servomechanism (PTOS)	62
3.3 Track-Settling: Initial Value Compensation (IVC)	63
3.3.1 Concept of IVC	63
3.3.1.1 Initialization of Controller State Variable . .	64
3.3.1.2 Design of Mode Switching Condition	64
3.3.2 IVC Design Method	65
3.3.3 Optimal Design of Mode Switching Condition	72
3.4 Track-Following: Single- and Multi-Rate Control	76
3.4.1 Single-Rate Control	76
3.4.1.1 Introduction	76
3.4.1.2 Lead Compensator and PI Controller	77
3.4.1.3 Notch Filter	82
3.4.1.4 Observer State Feedback Control	85
3.4.1.5 Pole Placement Technique	89
3.4.1.6 Optimal Control Design	93
3.4.2 Multi-Rate Control	94
3.4.2.1 Introduction	94
3.4.2.2 Problem Formulation	95
3.4.2.3 Multi-Rate Observer	97
3.5 Episode: Development of IVC Design Method in Industry .	99
Bibliography	101
4 Ultra-Fast Motion Control	107
<i>Mitsuo Hirata and Hiroshi Fujimoto</i>	
4.1 Vibration-Minimized Trajectory Design	107
4.1.1 Introduction	107
4.1.2 Final State Control (FSC) Theory	108
4.1.3 Vibration Minimized Trajectory Design Based on Final State Control	109
4.1.4 Application to Track-Seeking Control in HDDs	113
4.2 Perfect Tracking Control (PTC)	120
4.2.1 Introduction	120

4.2.2	PTC Theory	121
4.2.3	Vibration Suppression Using PTC	123
4.2.3.1	With MPVT	123
4.2.3.2	With Parallel Realization	124
4.2.3.3	With Modified Controllable Canonical Realization	125
4.2.4	Simulations and Experiments	126
4.2.4.1	Simulations Using Nominal Model	126
4.2.4.2	Experiments on HDDs	130
	Bibliography	134
5	Ultra-Precise Position Control	137
<i>Takenori Atsumi, Mitsuhiro Hirata, Hiroshi Fujimoto, and Nobutaka Bando</i>		
5.1	Phase-Stable Design for High Servo Bandwidth	138
5.1.1	Modeling of Controlled Object	139
5.1.2	Controller Design Based on Vector Locus	139
5.1.2.1	Relationship between Vector Locus and Sensitivity Transfer Function	142
5.1.2.2	Vector Locus of Controlled Object	142
5.1.3	Controller Design	145
5.1.3.1	Case 1: Gain-Stable Design for All Mechanical Resonant Modes	145
5.1.3.2	Case 2: Phase-Stable Design for Primary Mechanical Resonant Mode	146
5.1.3.3	Case 3: Phase-Stable Design for All Mechanical Resonant Modes	150
5.1.3.4	Comparison of Control Performances	150
5.2	Robust Control Using H_∞ Control Theory	155
5.2.1	Introduction	155
5.2.2	Mathematical Representation of Plant Uncertainties	156
5.2.2.1	Multiplicative Uncertainty	156
5.2.2.2	Additive Uncertainty	157
5.2.3	Robust Stability Problem	157
5.2.4	H_∞ Control Theory	159
5.2.5	Various H_∞ Control Problems	161
5.2.5.1	Sensitivity Minimization Problem	161
5.2.5.2	Mixed Sensitivity Problem	162
5.2.6	Application of H_∞ Control to HDDs	162
5.3	Multi-Rate H_∞ Control	169
5.3.1	Multi-Rate Discrete-Time H_∞ Control	169
5.3.2	Multi-Rate Sampled-Data H_∞ Control	171
5.4	Repetitive Control	177
5.4.1	Introduction	177
5.4.2	Repetitive Perfect Tracking Control (RPTC)	179

5.4.2.1	Discrete-Time Plant Model with Multi-Rate Hold	179
5.4.2.2	Design of PTC	181
5.4.3	Design of RPTC	182
5.4.4	Applications to RRO Rejection in HDDs	184
5.4.5	Experiments on RPTC	187
5.5	Acceleration Feedforward Control (AFC)	192
5.5.1	Introduction	192
5.5.2	Necessity for AFC	196
5.5.3	Types of AFC	198
5.5.3.1	Constant-Type AFC	199
5.5.3.2	Filter-Type AFC	200
5.5.3.3	Transfer Function-Type AFC	200
5.5.3.4	Adaptive Identification-Type AFC	202
5.5.4	Performance Evaluation for AFC	205
5.5.5	Applications of AFC	205
5.5.5.1	Application to Vehicles	209
5.5.5.2	Application to Industrial Robots	209
	Bibliography	209
6	Control Design for Consumer Electronics	213
	<i>Mitsuo Hirata, Shinji Takakura, and Atsushi Okuyama</i>	
6.1	Control System Design for Energy Efficiency	213
6.1.1	Interlacing Controller	214
6.1.2	Short-Track Seeking Using TDOF Control with IVC . .	217
6.2	Controller Design for Low Acoustic Noise Seek	222
6.2.1	Short-Span Seek Control for Low Acoustic Noise . . .	222
6.2.2	Long-Span Seek Control for Low Acoustic Noise . . .	231
6.3	Servo Control Design Based on SRS Analysis	243
6.3.1	Seeking Noise	243
6.3.2	Concept and Procedure of SRS Analysis	243
6.3.3	Models for SRS Analysis	244
6.3.4	Examples of SRS Analyses	246
6.3.5	Acoustic Noise Reduction Based on SRS Analysis . .	249
	Bibliography	256
7	HDD Benchmark Problem	259
	<i>Mitsuo Hirata</i>	
7.1	Public Release of the HDD Benchmark Problem	259
7.2	Plant Model	261
7.3	Disturbance Model	264
7.3.1	Force Disturbance	265
7.3.2	Flutter Disturbance	265
7.3.3	RRO	267
7.3.4	Measurement Noise	268

7.4	Overview of the HDD Benchmark Problem Version 3	269
7.5	Example of Controller Design	272
7.5.1	Track-Following Control Problem	273
7.5.2	Track-Seeking Control Problem	274
	Bibliography	280
Index		283