

Contents

1	Introduction	1
1.1	Classification of Sensors and Actuators	2
1.1.1	Magnetic Sensors	2
1.1.2	Linear and Latching Solenoid Actuators	3
1.1.3	Stepper Motors	5
1.1.4	Special Magnetic Devices	7
1.1.5	Rotary and Linear Actuators	8
1.2	Magnetic Materials and Technology	8
1.2.1	Soft Magnetic Materials	9
1.2.2	Hard Magnetic Materials	12
1.2.3	Coating Technologies	15
1.2.4	Magnetic Materials Market and Applications	16
2	Magnetic Sensors.....	21
2.1	Theory of Magnetic Sensors.....	23
2.2	Magnetic Sensor Analysis.....	24
2.3	VR Sensors	26
2.3.1	Conventional VR Sensors.....	27
2.3.2	High Performance VR Sensors	32
2.3.3	Sensors with Inserted Magnets	36
2.3.4	Front-Mounted-Magnet Sensors	43
2.3.5	Sensors with E-Shaped Magnetic Structure	45
2.3.6	Sensors with U-Shaped Magnetic Structure	46
2.3.7	Multiple Magnets VR Sensors	53
2.3.8	Dual-Magnet Sensors	53
2.3.9	Dual Sensor Arrangement.....	61
2.3.10	Distributed VR Sensors	63
2.4	Solid-State Sensors	70
2.4.1	Solid-State Sensor Analysis.....	71
2.4.2	Solid-State Sensor Design.....	72
2.4.3	Solid-State Sensor Test Results	75
2.5	Magnetic Sensor Applications	77
2.5.1	Magnetic Speed Sensor Requirements.....	77
2.5.2	Magnetic Speed Sensor Applications.....	78
2.5.3	Magnetic Position Sensor Applications	79
2.6	VR Sensor Noise.....	81
2.6.1	Math Model and Noise Analysis	81
2.6.2	Noise Problem Solutions	82
	Example 2.1	85
	Example 2.2	86
	Example 2.3	88

3	Linear Actuators	89
3.1	Mathematical Model for Linear Actuators	89
3.1.1	Symmetrical Analysis of Electromagnetic Devices	90
3.1.2	Electrical Network Equations	92
3.1.3	Mechanical Equations	94
3.1.4	Magnetic Forces	96
3.1.5	PWM Analysis.....	97
3.1.6	Solenoid Analysis and Simulations	102
3.2	Fast-Acting Actuators.....	106
3.2.1	Disk Solenoids.....	106
3.2.2	Plunger Solenoids.....	108
3.2.3	Ball Solenoids	110
3.2.4	Conical Solenoids	112
3.2.5	Optimization of Fast-Acting Actuators.....	115
3.3	Applications of Solenoid Actuators	118
3.3.1	Long Stroke Solenoid Fuel Pump	118
3.3.2	Gasoline Injectors	121
3.3.3	Natural Gas Injectors	125
3.3.4	Diesel Fuel Injectors	131
3.3.5	Compressor Solenoid Valves	137
3.3.6	Transmission Solenoids	140
Example 3.1		149
Example 3.2		151
4	Latching Linear Actuators	155
4.1	Latching Relays	155
4.1.1	Dynamics of Latching Relays	157
4.1.2	Bipolar Latching Relays.....	159
4.1.3	Unipolar Latching Relays.....	163
4.1.4	Latching Relay Analysis	165
4.1.5	Latching Relay Analysis and Tests	168
4.2	Latching Solenoids.....	173
4.2.1	Latching Solenoids with Moving Magnets	174
4.2.2	Latching Solenoids with Stationary Magnets	182
4.3	Latching Solenoid Applications.....	189
Example 4.1		190
5	Stepper Motors	191
5.1	Principles of Operation	191
5.2	Static Analysis of Stepper Motor.....	196
5.2.1	Static Torque Analysis.....	196
5.2.2	Magnetic-Circuit Analysis.....	201
5.2.3	Magnet Operating Point.....	207
5.2.4	Temperature Effect	210
5.2.5	Armature Reaction Effect	210
5.2.6	Experimental Results of Static Performance.....	211
5.3	Dynamic Analysis of Stepper Motor	217
5.3.1	Math Model of the Dynamic Operation.....	218
5.3.2	Stepper Motor Dynamic Simulation	221
5.3.3	Validation of the Dynamic Model	223

5.3.4	Effects of Various Parameters on Stepper Motor Performance	226
5.3.5	Experimental Results of Dynamic Performance	231
5.3.6	Evaluation of Viscous Damping Coefficient	233
5.3.7	Effects of Load Torque on Stepper Motor Performance	237
5.3.8	Stepper Motor Inductance in Dynamic Operation	242
Example 5.1:	Magnetic-Circuit Calculations.....	250
Example 5.2:	Static Torque Calculations	256
Example 5.3:	Magnetic Flux Calculations.....	257
6	Special Magnetic Devices.....	261
6.1	Magnetic Valves	261
6.1.1	Background.....	262
6.1.2	Heart Valve Requirements	262
6.1.3	Heart Valve Design Concept	265
6.1.4	Mathematical Model and Simulations	265
6.1.5	Optimized Design.....	269
6.1.6	Comparison and Test Results	272
6.2	Heart Pump.....	273
6.2.1	Heart Pump Requirements	274
6.2.2	Heart Pump Design Concept.....	275
6.2.3	Analytical Simulations and Optimized Design.....	275
6.3	Magnetorheological Fluid Solenoids	281
6.3.1	Background.....	281
6.3.2	Magnetorheological Fluid Solenoid Actuator.....	283
6.3.3	MR Fluid Applications	284
Example 6.1		287
Example 6.2		288
Example 6.3		288
7	Rotary Actuators	291
7.1	Disk Rotary Actuators.....	292
7.1.1	Disk Rotary Actuator Analysis.....	293
7.1.2	Disk Rotary Actuator Design	298
7.1.3	Disk Rotary Actuator Excitation Electromagnetic Circuit.....	298
7.1.4	Disk Rotary Actuator Toothed Magnetic Part	299
7.1.5	Disk Rotary Actuator PM.....	300
7.1.6	Disk Rotary Actuator Test Results.....	302
7.2	Claw Pole Rotary Actuators.....	304
7.2.1	Claw Pole Rotary Actuator Analysis.....	306
7.2.2	Claw Pole Rotary Actuator Design	309
7.2.3	Claw Pole Rotary Actuator Excitation Electromagnetic Circuit.....	309
7.2.4	Claw Pole Actuator Toothed Magnetic Part	310
7.2.5	Claw Pole Actuator PM.....	310
7.2.6	Claw Pole Rotary Actuator Test Results.....	313
7.3	Cylindrical Rotary Actuators	316
7.3.1	Cylindrical Rotary Actuator Analysis.....	317
7.3.2	Cylindrical Rotary Actuator 2D Analysis.....	318
7.3.3	Cylindrical Rotary Actuator 3D Analysis and Test Results	322
7.3.4	Cylindrical Rotary Actuator Design.....	325
7.3.5	Cylindrical Rotary Actuator PM.....	326

7.3.6	Cylindrical Rotary Actuator Excitation Electromagnetic Circuit	332
7.3.7	Cylindrical Rotary Actuator Toothed Magnetic Structure.....	332
7.4	Rotary Actuator Applications	333
7.4.1	Disk Rotary Actuator Application	335
7.4.2	Claw Pole Rotary Actuator Application	336
7.4.3	Cylindrical Rotary Actuator Application	338
Example 7.1		342
Example 7.2		343
Example 7.3		343
8	Addendum	345
8.1	Technology Development	345
8.1.1	Partnership.....	345
8.1.2	Competitiveness.....	346
8.1.3	Persistence.....	347
8.1.4	Technical Growth.....	348
8.2	Technology Valuation	349
8.2.1	Technical Attributes.....	349
8.2.2	Business Attributes	353
8.2.3	Financial Attributes	354
8.2.4	Technology Ranking.....	355
	Bibliography.....	357
	Index.....	363