## Contents

Preface		page ix
l	Introduction	1
	1. Systems under Consideration	1
	2. What Is Observability?	2
	3. Summary of the Book	2
	4. The New Observability Theory Versus	
	the Old Ones	3
	5. A Word about Prerequisites	4
	6. Comments	5
Pa	rt I. Observability and Observers	
2	Observability Concepts	9
	1. Infinitesimal and Uniform Infinitesimal	
	Observability	9
	2. The Canonical Flag of Distributions	11
	3. The Phase-Variable Representation	12
	4. Differential Observability and Strong Differential	
	Observability	14
	5. The Trivial Foliation	15
	6. Appendix: Weak Controllability	19
3	The Case $d_y \leq d_u$	20
	<ol> <li>Relation Between Observability and Infinitesimal</li> </ol>	
	Observability	20
	2. Normal Form for a Uniform Canonical Flag	22
	3. Characterization of Uniform Infinitesimal	
	Observability	24
	4. Complements	26
	5. Proof of Theorem 3.2	29

viii Contents

4	The Case $d_y > d_u$	36
	1. Definitions and Notations	37
	2. Statement of Our Differential Observability Results	40
	3. Proof of the Observability Theorems	42
	4. Equivalence between Observability and Observability	
	for Smooth Inputs	51
	5. The Approximation Theorem	57
	6. Complements	58
	7. Appendix	59
5	Singular State-Output Mappings	68
	1. Assumptions and Definitions	68
	2. The Ascending Chain Property	71
	3. The Key Lemma	73
	4. The $ACP(N)$ in the Controlled Case	78
	5. Globalization	81
	6. The Controllable Case	84
6	Observers: The High-Gain Construction	86
	<ol> <li>Definition of Observer Systems and Comments</li> </ol>	87
	2. The High-Gain Construction	95
	3. Appendix	120
Part II. Dynamic Output Stabilization and Applications		123
7	Dynamic Output Stabilization	125
	1. The Case of a Uniform Canonical Flag	126
	2. The General Case of a Phase-Variable Representation	132
	3. Complements	141
8	Applications	143
	1. Binary Distillation Columns	143
	2. Polymerization Reactors	163
Аp	Appendix	
Solutions to Part I Exercises		195
Bibliography		217
Index of Main Notations		221
Index		224