

Contents

Arrangement of Book	ix
Preface	xi
1. Basic Concepts.....	1
1.1 Introduction	1
1.2 The Railway Wheelset.....	2
1.3 Creep	6
1.4 Stability.....	8
1.5 Guidance.....	10
1.6 Suspension, Performance and Criteria.....	13
1.7 Suspension, Articulation and Curving.....	15
References	17
2. Equations of Motion	19
2.1 Introduction	19
2.2 Freedoms and Constraints	19
2.3 Wheel Rail Geometry	21
2.4 Contact Mechanics	32
2.4.1 Elasticity and Friction.....	32
2.4.2 Laws of Friction	32
2.4.3 Contact Between Wheel and Rail.....	32
2.4.4 Creep	33
2.4.4.1 Background	33
2.4.4.2 Formulation of the Creep Problem	34
2.4.4.3 Creep Forces for Small Creepages	36
2.4.4.4 Creep Forces for Arbitrary Creepages.....	37
2.4.4.5 An Approximate Theory for Arbitrary Creepages.....	37
2.4.4.6 Heuristic Approximations.....	39
2.4.4.7 Non-Hertzian Effects.....	39
2.4.5 Transient Effects.....	40
2.5 Creepages	40
2.6 Contact Forces.....	42
2.7 Kinematics of the Wheelset.....	44
2.8 Equations of Motion.....	46
2.9 Constrained Motion.....	48
2.10 Equations of Motion for Small Displacements.....	52
2.11 Equations of Motion for a Two-Axle Vehicle.....	61
References	66

3. Dynamics of the Wheelset	71
3.1 Introduction	71
3.2 The Unrestrained Wheelset	71
3.3 Root Locus for Small Motions of the Restrained Wheelset	76
3.4 Instability and Feedback	81
3.5 Amplitude Dependent Behaviour and Limit Cycles	84
3.6 Energy Balance	88
3.7 Dynamic Aspects of Guidance	89
3.8 Alternative Methods of Guidance	94
References	103
4. Guidance of the Two-Axle Vehicle	107
4.1 Introduction	107
4.2 Properties of the Stiffness Matrix	109
4.3 Steering on Large Radius Curves	111
4.4 Response to Cant Deficiency on Large Radius Curves	116
4.5 The Conflict Between Steering and Stability	118
4.6 Motion on Sharper Curves	121
4.7 Response to Misalignments	127
4.8 Flange Forces and Derailment	130
References	131
5. Dynamic Stability of the Two-Axle Vehicle	133
5.1 Introduction	133
5.2 Equations of Motion	135
5.3 Stiff and Flexible Vehicles	142
5.4 The Flexible Vehicle with Zero Suspension Damping	147
5.5 Damping and the Long Wheelbase Flexible Vehicle	151
5.6 Stability of the Flexible Vehicle in General	153
5.7 The Application of Cross-Bracing and Yaw Relaxation	159
5.8 The Stiff Vehicle or Bogie	160
5.9 The Three-Piece Bogie	169
References	169
6. The Bogie Vehicle	173
1 Introduction	173
2 Equations of Motion	175
3 Dynamics of the Conventional Bogie Vehicle	177
4 Steering and Stability of Multi-Axle Vehicles in General	182
5 Steering and Stability of a Generic Bogie Vehicle	185
6 Application to Specific Configurations	190
7 Stability of Bogie Vehicles with Steered Wheelsets	197
8 Simple Bogie Model	199
9 Stability of Simple Bogie Model	201
References	206

7. The Three-Axle Vehicle	209
7.1 Introduction	209
7.2 Steering and Stability of Three-Axle Vehicles	210
7.3 Steering with Unequal Conicities	215
7.4 Stability of Vehicle with Uniform Conicity	217
7.5 Stability with Unequal Conicities	225
7.6 Dynamic Response	230
References	232
8. Articulated Vehicles	235
8.1 Introduction	235
8.2 Steering and Stability.....	238
8.3 Application to Specific Configurations	244
8.4 Stability of an Articulated Three-Axle Vehicle.....	246
8.5 Stability and Response of an Articulated Four-Axle Vehicle.....	252
References	260
9. Unsymmetric Vehicles.....	261
9.1 Introduction	261
9.2 Stability Theorems for Rigid and Semi-Rigid Vehicles	263
9.3 Unsymmetric Rigid Vehicle	265
9.4 Steering of a Vehicle with Unsymmetric Inter-Wheelset Structure	267
9.5 Stability of a Two-Axle Articulated Vehicle.....	272
9.6 The Influence of Elastic Stiffness on Stability	276
9.7 Applications of Unsymmetry.....	279
References	281
Index	283