

Contents

To Our Families	v
Preface	vii
Chapter 1	1
Introduction	1
Chapter 2	13
Preliminaries	13
2.1 Review of Some Mathematical Background	14
2.2 Lyapunov Stability Theory	31
2.3 Frobenius Theorem	35
2.4 Sliding Control.....	39
2.5 Adaptive Control.....	45
2.6 Robust Adaptive Control	49
2.7 General Uncertainties.....	53
2.8 FAT-Based Adaptive Controller Design.....	57
2.9 Backstepping Procedure.....	66
2.10 Multiple-Surface Sliding Control	70
Chapter 3	77
Underactuated System Dynamics and Coordinate Transformation	77
3.1 Dynamics of Mechanical Systems	77
3.2 Underactuated Systems.....	80
3.3 Collocated Partial Feedback Linearization	82
3.4 Decoupling of General Underactuated Systems	84
3.5 Decoupling for 2-DOF Systems.....	88
3.6 Decoupling of Single-Input High-Order Systems.....	95
Chapter 4	100
Controller Design.....	100
4.1 Control Problem Formulation	100
4.2 Controller Design.....	104

4.3 Summary	117
Chapter 5.....	121
Cart Pole Systems	121
5.1 System Dynamics	122
5.2 Coordinate Transformation.....	125
5.3 Simulation Cases.....	126
Chapter 6.....	133
Overhead Cranes.....	133
6.1 System Dynamics	135
6.2 Coordinate Transformation.....	137
6.3 Simulation Cases.....	139
Chapter 7.....	147
TORA System.....	147
7.1 System Dynamics	148
7.2 Coordinate Transformation.....	151
7.3 Simulation Cases.....	152
Chapter 8.....	159
Rotary Inverted Pendulum.....	159
8.1 System Dynamics	160
8.2 Coordinate Transformation.....	163
8.3 Simulation Cases.....	164
Chapter 9.....	171
Vibration Absorber	171
9.1 System Dynamics	175
9.2 Coordinate Transformation.....	176
9.3 Steady State Performance Analysis	177
9.4 Simulation Cases.....	178
Chapter 10.....	189
Pendubot	189
10.1 System Dynamics	190
10.2 Coordinate Transformation.....	193
10.3 Simulation Cases.....	194
Bibliography	201
Index	217