

Contents

Preface to the SI Edition	X
Preface	xi
And anothing the area of the	
Chapter 1 Introduction to Statics	1
1.1 Introduction 1	
1.2 Newtonian Mechanics 3	
1.3 Fundamental Properties of Vectors 10	
1.4 Representation of Vectors Using Rectangular	
Components 18	
1.5 Vector Multiplication 27	
Chapter 2 Basic Operations with Force Systems	37
2.1 Introduction 37	-03 V
2.2 Equivalence of Vectors 37	
2.3 Force 38	
2.4 Reduction of Concurrent Force Systems 39	
2.5 Moment of a Force about a Point 49	
2.6 Moment of a Force about an Axis 60	
2.7 Couples 73	
2.8 Changing the Line of Action of a Force 86	
Chapter 3 Resultants of Force Systems	97
3.1 Introduction 97	
3.2 Reduction of a Force System to a Force and a Couple 97	
3.3 Definition of Resultant 105	
3.4 Resultants of Coplanar Force Systems 106	
3.5 Resultants of Three-Dimensional Systems 116	
3.6 Introduction to Distributed Normal Loads 128	
Chapter 4 Coplanar Equilibrium Analysis	143
4.1 Introduction 143	-73
4.2 Definition of Equilibrium 144	
Part A: Analysis of Single Bodies 144	
4.3 Free-Body Diagram of a Body 144	
4.4 Coplanar Equilibrium Equations 153	

4.5 Writing and Solving Equilibrium Equations 155 4.6 Equilibrium Analysis for Single-Body Problems 166 Part B: Analysis of Composite Bodies 179 4.7 Free-Body Diagrams Involving Internal Reactions 179 4.8 Equilibrium Analysis of Composite Bodies 190 4.9 Special Cases: Two-Force and Three-Force Bodies 200 Part C: Analysis of Plane Trusses 214 4.10 Description of a Truss 214 4.11 Method of Joints 215 4.12 Method of Sections 224	
	23
5.2 Definition of Equilibrium 238	
5.3 Free-Body Diagrams 238	
5.4 Independent Equilibrium Equations 249	
T I	
	28:
*6.2 Internal Force Systems 282	
*6.3 Analysis of Internal Forces 291	
	341
	77.
7.3 Problem Classification and Analysis 345	
7.4 Impending Tipping 361 / Tuning Street Head	
7.5 Angle of Friction; Wedges and Screws 369	
*7.6 Ropes and Flat Belts 379	
CAL REMITTED AT THE PROPERTY OF THE PARTY OF	
	6.01
	401
Curves 410	
0.4 Th CD C.11' 420	
A Property of the Control of the Con	
	4.6 Equilibrium Analysis for Single-Body Problems 166. Part B: Analysis of Composite Bodies 179 4.7 Free-Body Diagrams Involving Internal Reactions 179 4.8 Equilibrium Analysis of Composite Bodies 190 4.9 Special Cases: Two-Force and Three-Force Bodies 200 Part C: Analysis of Plane Trusses 214 4.10 Description of a Truss 214 4.11 Method of Joints 215 4.12 Method of Sections 224 Chapter 5 Three-Dimensional Equilibrium 5.1 Introduction 237 5.2 Definition of Equilibrium 238 5.3 Free-Body Diagrams 238 5.4 Independent Equilibrium Equations 249 5.5 Improper Constraints 252 5.6 Writing and Solving Equilibrium Equations 253 5.7 Equilibrium Analysis 263 Chapter 6 Beams and Cables *6.1 Introduction 281 Part A: Beams 282 *6.2 Internal Force Systems 282 *6.3 Analysis of Internal Forces 291 *6.4 Area Method for Drawing V- and M-Diagrams 303 Part B: Cables 318 *6.5 Cables under Distributed Loads 318 *6.6 Cables under Concentrated Loads 330 Chapter 7 Dry Friction 7.1 Introduction 341 7.2 Coulomb's Theory of Dry Friction 342 7.3 Problem Classification and Analysis 345 7.4 Impending Tipping 361 7.5 Angle of Friction; Wedges and Screws 369 *7.6 Ropes and Flat Belts 379 *7.7 Disk Friction 386 *7.8 Rolling Resistance 391 Chapter 8 Centroids and Distributed Loads 8.1 Introduction 401 8.2 Centroids of Plane Areas and Curves 401 8.3 Centroids of Plane Areas and Curves 401 8.3 Centroids of Curved Surfaces, Volumes, and Space Curves 419

^{*} Indicates optional articles

8.6 Distributed Normal Loads 450	
Chapter 9 Moments and Products of Inertia of Areas	471
9.1 Introduction 471	
9.2 Moments of Inertia of Areas and Polar Moments of	
Inertia 472	
9.3 Products of Inertia of Areas 492	
9.4 Transformation Equations and Principal Moments of Inertia of Areas 500	
*9.5 Mohr's Circle for Moments and Products of Inertia 508	
Chapter 10 Virtual Work and Potential Energy	523
*10.1 Introduction 523	3-3
*10.2 Virtual Displacements 524	
*10.3 Virtual Work 525	
*10.4 Method of Virtual Work 528	
*10.5 Instant Center of Rotation 539	
*10.6 Equilibrium and Stability of Conservative Systems 548	
Appendix A Numerical Integration	559
A.1 Introduction 559	
A.2 Trapezoidal Rule 560	
A.3 Simpson's Rule 560	
Appendix B Finding Roots of Functions	563
B.1 Introduction 563	inneta.
B.2 Newton's Method 563	
B.3 Secant Method 564	
Appendix C Densities of Common Materials	567
Answers to Even-Numbered Problems	569
Index	576