

Contents

Biography	vii
Preface to the First Edition	xvii

CHAPTER 1 Computational Modeling	1
1.1 Introduction	1
1.2 Physical Problems in Engineering	4
1.3 Computational Modeling Using FEM	4
1.3.1 Modeling of the Geometry	5
1.3.2 Meshing	6
1.3.3 Material or Medium Properties	8
1.3.4 Boundary, Initial, and Loading Conditions	8
1.4 Solution Procedure	8
1.4.1 Discrete System Equations	8
1.4.2 Equation Solvers	9
1.5 Results Visualization	10
 CHAPTER 2 Briefing on Mechanics for Solids and Structures	 13
2.1 Introduction	14
2.2 Equations for Three-Dimensional Solids	16
2.2.1 Stress and Strain	16
2.2.2 Constitutive Equations	18
2.2.3 Dynamic Equilibrium Equations	19
2.2.4 Boundary Conditions	21
2.3 Equations for Two-Dimensional Solids	22
2.3.1 Stress and Strain	22
2.3.2 Constitutive Equations	24
2.3.3 Dynamic Equilibrium Equations	25
2.4 Equations for Truss Members	26
2.4.1 Stress and Strain	27
2.4.2 Constitutive Equations	27
2.4.3 Dynamic Equilibrium Equations	27
2.5 Equations for Beams	30
2.5.1 Stress and Strain	30
2.5.2 Constitutive Equations	31
2.5.3 Moments and Shear Forces	31
2.5.4 Dynamic Equilibrium Equations	33

2.6	Equations for Plates	34
2.6.1	Stress and Strain.....	35
2.6.2	Constitutive Equations	36
2.6.3	Moments and Shear Forces.....	36
2.6.4	Dynamic Equilibrium Equations	38
2.6.5	Reissner–Mindlin Plate.....	38
2.7	Remarks	40
2.8	Review Questions	40

CHAPTER 3 Fundamentals for Finite Element Method..... 43

3.1	Introduction.....	44
3.2	Strong and Weak Forms: Problem Formulation	44
3.3	Hamilton’s Principle: A Weak Formulation.....	45
3.3.1	Hamilton’s Principle	45
3.3.2	Minimum Total Potential Energy Principle	47
3.4	FEM Procedure.....	47
3.4.1	Domain Discretization	47
3.4.2	Displacement Interpolation.....	49
3.4.3	Standard Procedure for Constructing Shape Functions	50
3.4.4	Properties of the Shape Functions	54
3.4.5	Formulation of Finite Element Equations in Local Coordinate System.....	63
3.4.6	Coordinate Transformation	67
3.4.7	Assembly of Global FE Equation	68
3.4.8	Imposition of Displacement Constraints.....	69
3.4.9	Solving the Global FE Equation	69
3.5	Static Analysis	69
3.6	Analysis of Free Vibration (Eigenvalue Analysis).....	69
3.7	Transient Response	71
3.7.1	Central Difference Algorithm	72
3.7.2	Newmark’s Method (Newmark, 1959)	75
3.8	Remarks	76
3.8.1	Summary of Shape Function Properties	76
3.8.2	Sufficient Requirements for FEM Shape Functions	76
3.8.3	Recap of FEM Procedure.....	77
3.9	Review Questions	78

CHAPTER 4 FEM for Trusses..... 81

4.1	Introduction.....	81
4.2	FEM Equations	82
4.2.1	Shape Function Construction.....	82

4.2.2 Strain Matrix	85
4.2.3 Element Matrices in the Local Coordinate System	86
4.2.4 Element Matrices in the Global Coordinate System	87
4.2.5 Boundary Conditions	91
4.2.6 Recovering Stress and Strain	92
4.3 Worked Examples	92
4.3.1 Properties of the FEM	94
4.4 High Order One-Dimensional Elements	103
4.5 Review Questions	105
CHAPTER 5 FEM for Beams	111
5.1 Introduction	111
5.2 FEM Equations	112
5.2.1 Shape Function Construction	112
5.2.2 Strain Matrix	115
5.2.3 Element Matrices	116
5.3 Remarks	118
5.4 Worked Examples	118
5.5 Case Study: Resonant Frequencies of Micro-Resonant Transducer	122
5.5.1 Modeling	123
5.5.2 ABAQUS Input File	124
5.5.3 Solution Process	127
5.5.4 Results and Discussion	128
5.5.5 Comparison with ANSYS	130
5.6 Review Questions	132
CHAPTER 6 FEM for Frames	135
6.1 Introduction	135
6.2 FEM Equations for Planar Frames	137
6.2.1 The Idea of Superposition	137
6.2.2 Equations in the Local Coordinate System	137
6.2.3 Equations in the Global Coordinate System	140
6.3 FEM Equations for Space Frames	142
6.3.1 Equations in the Local Coordinate System	142
6.3.2 Equations in the Global Coordinate System	144
6.4 Remarks	149
6.5 Case Study: Finite Element Analysis of a Bicycle Frame	150
6.5.1 Modeling	151
6.5.2 ABAQUS Input File	152
6.5.3 Solution Processes	154

6.5.4 Results and Discussion	155
6.6 Review Questions	157
CHAPTER 7 FEM for Two-Dimensional Solids.....	161
7.1 Introduction.....	162
7.2 Linear Triangular Elements	164
7.2.1 Field Variable Interpolation	164
7.2.2 Shape Function Construction.....	166
7.2.3 Area Coordinates.....	170
7.2.4 Strain Matrix	172
7.2.5 Element Matrices	174
7.3 Linear Rectangular Elements.....	176
7.3.1 Shape Function Construction.....	176
7.3.2 Strain Matrix	179
7.3.3 Element Matrices	179
7.3.4 Gauss Integration	180
7.4 Linear Quadrilateral Elements.....	183
7.4.1 Coordinate Mapping	183
7.4.2 Strain Matrix	186
7.4.3 Element Matrices	187
7.4.4 Remarks	188
7.5 Elements for Axisymmetric Structures	188
7.6 Higher Order Elements—Triangular Element Family.....	191
7.6.1 General Formulation of Shape Functions	191
7.6.2 Quadratic Triangular Elements	193
7.6.3 Cubic Triangular Elements	194
7.7 Rectangular Elements	195
7.7.1 Lagrange Type Elements.....	195
7.7.2 Serendipity Type Elements	196
7.8 Elements with Curved Edges.....	200
7.9 Comments on Gauss Integration.....	201
7.10 Case Study: Side Drive Micro-Motor.....	201
7.10.1 Modeling.....	203
7.10.2 ABAQUS Input File.....	204
7.10.3 Solution Process	207
7.10.4 Results and Discussion	208
7.11 Review Questions	211
CHAPTER 8 FEM for Plates and Shells	219
8.1 Introduction.....	219
8.2 Plate Elements	220

8.2.1	Shape Functions	224
8.2.2	Element Matrices	225
8.2.3	Higher Order Elements	227
8.3	Shell Elements	227
8.3.1	The Idea of Superposition	228
8.3.2	Elements in the Local Coordinate System	228
8.3.3	Elements in the Global Coordinate System	232
8.4	Remarks	233
8.5	Case Study: Natural Frequencies of the Micro-Motor	233
8.5.1	Modeling	233
8.5.2	ABAQUS Input File	234
8.5.3	Solution Process	236
8.5.4	Results and Discussion	237
8.6	Case Study: Transient Analysis of a Micro-Motor	240
8.6.1	Modeling	241
8.6.2	ABAQUS Input File	242
8.6.3	Solution Process	244
8.6.4	Results and Discussion	245
8.7	Review Questions	247

CHAPTER 9 FEM for 3D Solid Elements 249

9.1	Introduction	249
9.2	Tetrahedron Element	250
9.2.1	Strain Matrix	250
9.2.2	Element Matrices	256
9.3	Hexahedron Element	261
9.3.1	Strain Matrix	261
9.3.2	Element Matrices	266
9.3.3	Using Tetrahedrons to form Hexahedrons	269
9.4	Higher Order Elements	269
9.4.1	Tetrahedron Elements	269
9.4.2	Brick Elements	272
9.5	Elements with Curved Surfaces	277
9.6	Case Study: Stress and Strain Analysis of a Quantum Dot Heterostructure	277
9.6.1	Modeling	279
9.6.2	ABAQUS Input File	282
9.6.3	Solution Process	284
9.6.4	Results and Discussion	285
9.7	Review Questions	286

CHAPTER 10 Special Purpose Elements.....	289
10.1 Introduction.....	289
10.2 Crack Tip Elements.....	289
10.3 Methods for Infinite Domains.....	293
10.3.1 Infinite Elements Formulated by Mapping	294
10.3.2 Gradual Damping Elements.....	297
10.3.3 Coupling of FEM and the Boundary Element Method.....	297
10.3.4 Coupling of FEM and the Strip Element Method.....	298
10.4 Finite Strip Elements	298
10.5 Strip Element Method.....	298
10.6 Meshfree Methods	299
10.7 S-FEM.....	299
 CHAPTER 11 Modeling Techniques.....	 301
11.1 Introduction.....	302
11.2 CPU Time Estimation	303
11.3 Geometry Modeling.....	304
11.4 Meshing	306
11.4.1 Mesh Density	306
11.4.2 Element Distortion.....	307
11.5 Mesh Compatibility	310
11.5.1 Different Order of Elements	310
11.5.2 Straddling Elements.....	312
11.6 Use of Symmetry	313
11.6.1 Mirror Symmetry or Plane Symmetry	314
11.6.2 Axial Symmetry	318
11.6.3 Cyclic Symmetry	321
11.6.4 Repetitive Symmetry	322
11.7 Modeling of Offsets	322
11.7.1 Methods for Modeling Offsets.....	322
11.7.2 Creation of MPC Equations for Offsets.....	325
11.8 Modeling of Supports	328
11.9 Modeling of Joints	328
11.10 Other Applications of MPC Equations	332
11.10.1 Modeling of Symmetric Boundary Conditions	332
11.10.2 Enforcement of Mesh Compatibility	334
11.10.3 Modeling of Constraints by Rigid Body Attachment.....	335
11.11 Implementation of MPC Equations	336
11.11.1 Lagrange Multiplier Method	338

11.11.2	Penalty Method.....	338
11.12	Review Questions	339
CHAPTER 12	FEM for Heat Transfer Problems	347
12.1	Field Problems	348
12.1.1	Heat Transfer in a Two-Dimensional Fin	348
12.1.2	Heat Transfer in a Long Two-Dimensional Body	349
12.1.3	Heat Transfer in a One-Dimensional Fin.....	350
12.1.4	Heat Transfer Across a Composite Wall	351
12.1.5	Torsional Deformation of a Bar	352
12.1.6	Ideal Irrotational Fluid Flow.....	353
12.1.7	Acoustic Problems	353
12.2	Weighted Residual Approach for FEM.....	354
12.3	1D Heat Transfer Problem	355
12.3.1	One-Dimensional Fin	355
12.3.2	Direct Assembly Procedure	361
12.3.3	Worked Example.....	362
12.3.4	Remarks	364
12.3.5	Composite Wall.....	365
12.3.6	Worked Example.....	366
12.4	2D Heat Transfer Problem	370
12.4.1	Element Equations.....	370
12.4.2	Triangular Elements.....	373
12.4.3	Rectangular Elements	375
12.4.4	Boundary Conditions and Vector $b^{(e)}$	377
12.4.5	Point Heat Source or Sink	384
12.5	Summary	386
12.6	Case Study: Temperature Distribution of Heated Road Surface	386
12.6.1	Modeling.....	387
12.6.2	ABAQUS Input File.....	388
12.6.3	Results and Discussion	390
12.7	Review Questions	390
CHAPTER 13	Using FEM Software Packages	397
13.1	Introduction.....	397
13.2	Basic Building Block: Keywords and Data Lines	399
13.3	Using Sets	400
13.4	ABAQUS Input Syntax Rules.....	401
13.4.1	Keyword Lines.....	401

13.4.2	Data Lines.....	401
13.4.3	Lables.....	402
13.5	Defining a Finite Element Model in ABAQUS.....	402
13.5.1	Model Data	403
13.5.2	History Data.....	404
13.5.3	An Example of a Cantilever Beam Problem.....	405
13.6	General Procedures.....	411
13.7	Remarks (Example Using a GUI: ANSYS).....	414
References		423
Index		425