

# Contents

Preface	<i>page xv</i>
Acknowledgments	xix
List of Abbreviations	xxiii
Nomenclature	xxvii
<b>1. Introduction to Computational Aerodynamics</b>	<b>1</b>
1.1 Introduction	2
1.2 The Goals of Computational Aerodynamics	6
1.3 The Intelligent User	7
1.4 A Bit of Computational Aerodynamics History	10
1.5 What Can Computational Aerodynamics Do Today and Tomorrow?	19
1.5.1 Commercial Aircraft Applications	19
1.5.2 Military Aircraft Applications	22
1.6 Integration of CA and Experiments	25
1.7 Design, Analysis, and Multidisciplinary Optimization	27
1.8 The Computational Aerodynamics Process	29
1.8.1 Geometry Modeling	31
1.8.2 Grid Generation	32
1.8.3 Flow Solution	33
1.8.4 Post Processing	34
1.8.5 Code Validation	35
1.9 Computational Aerodynamics Users and Errors	37
1.10 Scope, Purpose, and Outline of the Book	38
1.11 Project	40
1.12 References	40
<b>2. Computers, Codes, and Engineering</b>	<b>45</b>
2.1 Introduction	46
2.2 From Engineering Methods to High-Performance Computing	47
2.2.1 Semi-Empirical Methods	48
2.2.2 Linear Potential Flow Methods	55
2.2.3 CFD Methods	55
2.2.4 When Should You Use a Given Method?	55

2.3	Computing Systems	59
2.3.1	Why CA Requires Large Computers	61
2.3.2	CA Historical Development	63
2.3.3	Computer Measures of Merit	66
2.3.4	Parallel Computer Scalability	71
2.4	Computer Codes: Verification, Validation, and Certification	78
2.5	Some Comments on Programming	82
2.6	Elements of a Solution	86
2.7	Projects	89
2.8	References	90
<b>3.</b>	<b>Getting Ready for Computational Aerodynamics:</b>	
	<b>Fluid Mechanics Foundations</b>	<b>93</b>
3.1	Introduction	94
3.2	Governing Equations of Fluid Mechanics	94
3.3	Derivation of Governing Equations	98
3.3.1	Conservation of Mass: The Continuity Equation	100
3.3.2	Conservation of Momentum and the Substantial Derivative	104
3.3.2.1	Substantial Derivative	104
3.3.2.2	Forces	107
3.3.3	The Energy Equation	113
3.4	Solution of the Set of Governing Equations	116
3.5	Standard Forms and Terminology of Governing Equations	117
3.5.1	Nondimensionalization	118
3.5.2	Use of Divergence Form	118
3.5.3	The “Standard” or “Vector” Form of the Equations	120
3.6	Boundary Conditions, Initial Conditions, and the Mathematics	
	Classification of Partial Differential Equations (PDEs)	124
3.6.1	Hyperbolic Type	126
3.6.2	Parabolic Type	126
3.6.3	Elliptic Type	127
3.6.4	Equations of Mixed Type	127
3.6.5	Elaboration on Characteristics	128
3.7	Hyperbolic PDEs	130
3.8	Parabolic PDEs	131
3.9	Elliptic PDEs	132
3.10	Boundary Conditions	133
3.11	Using and Simplifying These Equations: High- to	
	Low-Fidelity Flowfield Models	138
3.12	Inviscid Flow Models	138
3.12.1	Potential Flow	139
3.12.2	Small Disturbance Expansion of the Full Potential	
	and Energy Equation	141
3.12.3	Transonic Small Disturbance Equation	144

3.12.4 Prandtl-Glauert Equation	145
3.12.5 Incompressible Irrotational Flow: Laplace's Equation	146
3.13 Viscous Flow Models	147
3.13.1 Thin-Layer Navier-Stokes Equations	149
3.13.2 Parabolized Navier-Stokes Equations	152
3.13.3 Boundary-Layer Equations	153
3.14 Examples of Zones of Application	155
3.15 Requirements for a Complete Problem Formulation	156
3.16 Exercises	157
3.17 References	158
<b>4. Getting Ready for Computational Aerodynamics:</b>	
<b>Aerodynamic Concepts</b>	<b>161</b>
4.1 Introduction	162
4.2 Review of Potential Flow Theory	163
4.2.1 Vorticity	164
4.2.2 Simplified Equations of Motion	167
4.3 Potential Flow Applications	168
4.3.1 Flow Over a Circular Cylinder	169
4.3.2 Flow Over a Circular Cylinder with Circulation	173
4.4 Applications to Airfoils	177
4.4.1 Conformal Mapping	177
4.4.2 Singularity Distribution Approaches	178
4.4.3 Kutta Condition	178
4.5 Boundary Layers and Viscous Effects	179
4.5.1 Boundary Layer Concepts	179
4.5.1.1 Laminar Boundary Layers	180
4.5.1.2 Turbulent Boundary Layers	181
4.5.1.3 Relative Features of Boundary Layers	182
4.5.2 Skin Friction Estimation	184
4.6 Airfoil Aerodynamics	188
4.6.1 Airfoil Terminology	189
4.6.2 Forces and Moments on an Airfoil	189
4.6.3 Airfoil Aerodynamic Coefficients	192
4.6.4 Airfoil Lift and Drag Variations	192
4.6.5 NACA Airfoil Families	195
4.6.6 How to Use NACA Airfoil Data	196
4.6.7 Factors That Affect Airfoil Aerodynamics	198
4.6.7.1 Reynolds Number	198
4.6.7.2 Camber	198
4.6.7.3 Thickness	199
4.6.8 How Airfoils Work	199
4.6.9 Thin Airfoil Theory	204

4.7	Wing Aerodynamics	208
4.7.1	Wing Terminology	209
4.7.2	Wing Aerodynamic Coefficients	210
4.7.3	The Vortex Filament	211
4.7.4	Prandtl's Lifting Line Theory	213
4.7.5	Subsonic Compressibility Effects	218
4.8	Transonic Aerodynamics	222
4.8.1	Transonic Theories	227
4.8.2	Supercritical Airfoils	227
4.8.3	Korn Airfoil Equation	229
4.8.4	Wing Sweep	230
4.8.5	Korn Wing Equation	235
4.9	Supersonic Aerodynamics	237
4.9.1	Supersonic Linear Theory and Airfoil Aerodynamics	240
4.9.2	Volumetric Wave Drag	245
4.9.3	Wing Aerodynamics	247
4.10	Hypersonic Aerodynamics	249
4.10.1	Importance of Temperature in Hypersonic Flow	250
4.10.2	Newtonian and Modified Newtonian Flow Theory	252
4.10.3	Aerodynamic Heating	253
4.10.4	Engine/Airframe Integration	255
4.11	Exercises	258
4.12	Projects	259
4.13	References	260
<b>5.</b>	<b>Classical Linear Theory Computational Aerodynamics</b>	<b>264</b>
5.1	Introduction	265
5.2	Panel Methods	267
5.2.1	The Integral Equation for the Potential	269
5.2.2	An Example of a Panel Code: The Classic Hess and Smith Method	277
5.2.3	Program <i>PANEL</i>	281
5.2.4	Geometry and Design	290
5.2.4.1	Effects of Shape Changes on Pressure Distributions	291
5.2.4.2	Shape for a Specified Pressure Distribution	291
5.2.5	Issues in the Problem Formulation for 3D Potential Flow Over Aircraft	292
5.2.6	Example Applications of Panel Methods	294
5.2.7	Using Panel Methods	299
5.2.7.1	Commonsense Rules for Panels	301
5.2.7.2	What a Panel Method Can and Cannot Do	301
5.2.8	Advanced Panel Methods: What Is a "Higher Order" Panel Method?	301

5.2.9	Current Standard Panel Method Programs: A Brief Survey	302
5.2.9.1	<i>PAN AIR</i>	302
5.2.9.2	<i>VSAERO</i>	302
5.2.9.3	Woodward Code	304
5.2.9.4	<i>PMARC</i>	304
5.3	Vortex Lattice Methods	305
5.3.1	Boundary Conditions on the Mean Surface and the Pressure Relation	307
5.3.1.1	Linearized Form of the Boundary Condition	309
5.3.1.2	Transfer of the Boundary Conditions	310
5.3.1.3	Decomposition of Boundary Conditions into Camber/Thickness/Alpha	311
5.3.1.4	Thin Airfoil Theory Pressure Relation	312
5.3.1.5	$\Delta C_p$ due to Camber/Alpha (Thickness Effects Cancel!)	313
5.3.2	The Classical Vortex Lattice Method	317
5.3.3	Examples of the Use and Accuracy of the Vortex Lattice Method	323
5.3.3.1	The Warren 12 Test Case	323
5.3.3.2	Isolated Swept Wing	325
5.3.3.3	Wing-Body-Tail	326
5.3.3.4	Control Surface Deflection	328
5.3.3.5	Pitch and Roll Damping Estimation	328
5.3.3.6	Slender Lifting Body Results	329
5.3.3.7	Non-Planar Results	331
5.3.3.8	Ground Effects and Dihedral Effects	332
5.3.4	Inverse Design Methods and Program DesCam	334
5.3.5	Alternate and Advanced VLM Methods	336
5.3.6	Unsteady Flow Extension	337
5.3.7	Vortex Lattice Method Summary	338
5.4	Projects	339
5.5	References	344
<b>6.</b>	<b>Introduction to Computational Fluid Dynamics</b>	<b>350</b>
6.1	Introduction	351
6.2	Options for Numerically Solving the Navier-Stokes Equations	353
6.2.1	Finite Difference Methods	354
6.2.2	Finite Volume Methods	355
6.2.3	Finite Element/Pseudo Spectral Methods	356
6.3	Approximations to Derivatives	358
6.4	Finite Difference Methods	359
6.5	Representing Partial Differential Equations	367
6.5.1	Discretization	369
6.5.2	Consistency	370

6.5.3 Stability	370
6.5.4 Convergence	370
6.6 Stability Analysis	371
6.6.1 Fourier or Von Neumann Stability Analysis	372
6.6.2 Examples of Stability and Instability	374
6.7 The Wave Equation	377
6.7.1 Forward Difference in $x$	379
6.7.2 Central Difference in $x$	379
6.7.3 Backward Difference in $x$	379
6.7.4 Lax Method	380
6.7.5 Lax-Wendroff Method	381
6.7.6 MacCormack Method	381
6.8 Truncation Error Analysis of the Wave Equation: The Modified Equation	383
6.9 The Heat Equation	385
6.9.1 Explicit Scheme	386
6.9.2 Implicit Scheme	387
6.10 Laplace's Equation	389
6.11 The Finite Volume Method	391
6.12 Time Integration and Differences	396
6.12.1 Explicit Time Integration	397
6.12.1.1 First-Order Time Accuracy	397
6.12.1.2 Second-Order Time Accuracy	398
6.12.1.3 General Form of Backward Time Difference	398
6.12.1.4 Runge-Kutta Time Integration	399
6.12.2 Implicit Time Integration	400
6.12.3 Subiterations	401
6.12.4 Solution Method for Time Integration	402
6.13 Boundary Conditions	403
6.13.1 Farfield Boundary Conditions	403
6.13.2 Solid Wall Boundary Conditions	405
6.13.3 Numerical Representation of Boundary Conditions	409
6.14 Solution of Algebraic Equations	410
6.14.1 Dense Matrix	411
6.14.2 Sparse and Banded Matrix	411
6.14.3 General Sparse Matrix	412
6.14.4 Point Jacobi and Point Gauss-Seidel	413
6.14.5 Gauss-Seidel and Successive Over-Relaxation	413
6.14.6 Successive Line Over-Relaxation	415
6.14.7 Approximate Factorization	416
6.14.8 Multigrid Method	420
6.14.9 The Delta Form	421
6.15 Program <i>THINFOIL</i>	421

6.16	Modern Methods	425
6.16.1	Finite Difference Methods	425
6.16.2	Higher-Order Methods	428
6.16.3	Finite Volume Methods	430
6.17	Projects	439
6.18	References	443
<b>7.</b>	<b>Geometry and Grids: Key Considerations in Computational Aerodynamics</b>	<b>448</b>
7.1	Introduction	449
7.2	Surface Shape Development: Lofting Techniques	449
7.3	Computational Grid Overview	454
7.4	Grid or Mesh Types	455
7.5	Structured Grids	463
7.5.1	Topologies	463
7.6	Methods for Creating Structured Grids	468
7.6.1	Algebraic Grid Generation and Stretching/Clustering	472
7.6.2	Conformal Transformation	475
7.6.3	Elliptic Grid Generation	477
7.6.4	Hyperbolic Grid Generation	480
7.7	Unstructured Meshes	481
7.7.1	Cell Types	482
7.8	Methods for Creating Unstructured Meshes	484
7.8.1	Delaunay Triangulation	484
7.8.2	Advancing Front/Advancing Layer	486
7.8.3	Octree	488
7.9	Cartesian Grids	489
7.10	Grid Adaption	493
7.11	Grid Properties that Affect Solution Accuracy	497
7.11.1	Outer Boundary Size	497
7.11.2	Structured Cell Geometry	499
7.11.2.1	Jacobian	499
7.11.2.2	Cell Shape	500
7.11.2.3	Cell Orthogonality at a Surface Boundary	501
7.11.2.4	Cell Stretching	502
7.11.3	Unstructured Cell Geometry	505
7.11.3.1	Flow Alignment and Boundary Layer Gradients	505
7.11.3.2	Cell Planariness	506
7.11.3.3	Cell Skew and Smoothness	508
7.11.3.4	Cell Isotropy and Spacing	510
7.11.4	Viscous Grid Requirements	511
7.12	Grid Sensitivity Studies	513

7.13	Examples of Grids for Complex Geometries	516
7.13.1	Ranger Jet Aircraft Inviscid Block-structured Grid	516
7.13.2	X-31 Viscous Block Structured Grid	518
7.13.3	Block Structured Grid for Helicopter with Sliding Interface Rotor	520
7.13.4	Unstructured High Lift Commercial Transport	520
7.13.5	Unstructured Mesh for Aircraft with Stores	522
7.13.6	C-130 Unstructured Chimera Mesh with Ring-Slot Parachute	522
7.13.7	V-22 Rotorcraft with Cartesian Overset Grids	524
7.14	Current Grid Generation Software and Data Structures	525
7.15	Projects	528
7.16	References	530
<b>8.</b>	<b>Viscosity and Turbulence Modeling</b>	<b>539</b>
8.1	Introduction	540
8.2	Types of Viscous Effects	540
8.3	Laminar Flow	543
8.4	Transition	545
8.5	Turbulent Flow	554
8.6	Characteristics of Turbulence	555
8.7	Turbulence Modeling Approaches	560
8.8	Reynolds-Averaged Navier-Stokes (RANS)	563
8.8.1	Mass-Weighted Averaging	566
8.8.2	Taxonomy of Turbulence Models	567
8.8.3	Prandtl's Mixing-Length Theory – An Example of a Zero-Equation Model	569
8.8.4	Examples of the Use of Various RANS Models	572
8.8.5	FLOMANIA Project Results	583
8.8.6	AIAA Drag Prediction Workshop results	584
8.9	Large-Eddy Simulation	590
8.9.1	Spatial Filtering	591
8.9.2	Subgrid Scale Models	592
8.9.3	Example LES Applications	593
8.10	Hybrid Approach (RANS/LES)	595
8.10.1	Detached-Eddy Simulation	596
8.10.2	Delayed Detached-Eddy Simulation	599
8.10.3	Improved Delayed Detached-Eddy Simulation	602
8.10.4	DESider Results	603
8.11	Direct Numerical Simulation	607
8.12	References	610
<b>9.</b>	<b>Flow Visualization: The Art of Computational Aerodynamics</b>	<b>617</b>
9.1	Introduction	618
9.2	Flow Visualization Background	620



9.3	How Flow Visualization Works	627
9.3.1	Smooth Contour Lines	628
9.3.2	Three-Dimensional Vector Plots	630
9.3.3	Streamlines	631
9.3.4	Flow Function Computation	632
9.4	How to View Scalar Properties	634
9.5	How to View Vector Properties	637
9.5.1	Commonly Used Vectors in Fluid Dynamics and Flow Visualization	637
9.5.1.1	Vorticity	638
9.5.1.2	Helicity Density and Relative Helicity	638
9.5.1.3	$Q$ -Criterion	639
9.5.1.4	Shear Stress Vector	639
9.5.2	Examples of vector flow visualization	640
9.5.2.1	Vector Arrows	640
9.5.2.2	Streamline/Stream Ribbons	641
9.5.2.3	Vortex Visualization Using Vector Magnitudes	643
9.5.2.4	Vortex Visualization Using the $Q$ -Criterion	646
9.5.2.5	Vortex Visualization Using Vortex Tracking	647
9.5.3	Skin Friction Lines	647
9.6	Newer Flow Visualization Approaches	650
9.6.1	Line Integral Convolution	650
9.6.2	Numerical Schlieren	651
9.6.3	Feature Extraction	653
9.6.4	Unsteady Flow and Movies	657
9.7	Projects	659
9.8	References	659
<b>10.</b>	<b>Applications of Computational Aerodynamics</b>	<b>662</b>
10.1	Introduction	663
10.2	Getting to Know Flowfields	663
10.3	Transonic Aerodynamics Prediction	669
10.3.1	Brief Review of Methodology Development for Transonic Flow Calculations	669
10.3.2	Airfoils	670
10.3.3	Wings	672
10.3.4	Drag Prediction	673
10.3.5	Fighter Aircraft Design	676
10.4	Supersonic Aerodynamics Prediction	680
10.4.1	Initial Application of CFD at Supersonic Speeds	680
10.4.2	Application of CFD to a Supersonic Configuration	683
10.4.3	Application to Low Sonic Boom Aircraft Design	685
10.5	Hypersonic Aerodynamics Prediction	690
10.6	Aerodynamic Design and MDO	696
10.6.1	High Speed Civil Transport Example	699

10.6.2	Truss-Braced Wing Example	701
10.7	Integration of Computational and Experimental Work	704
10.7.1	Pros and Cons of Experiments	704
10.7.2	Pros and Cons of Computations	705
10.7.3	Delta Wing with Periodic Suction and Blowing for Flow Control	706
10.7.4	Pitching UCAV Configuration	708
10.7.5	C-130 Airdrop Configuration	711
10.7.6	Closed-Loop Flow Control	712
10.7.7	Data Assimilation	716
10.8	Current Applications of Potential Flow Codes	718
10.8.1	Compressible Vortex Lattice Method	719
10.8.2	Transonic Lifting-Line Method	719
10.8.3	Unsteady Vortex-Lattice Method for Aeroelasticity	720
10.8.4	Meshless Full Potential Solver	721
10.9	The Future of Computational Aerodynamics	721
10.10	Projects	724
10.11	References	724
<b>Appendix A Geometry for Aerodynamicists</b>		<b>731</b>
<b>Appendix B Sources of Experimental Data for Code Validation</b>		<b>766</b>
<b>Appendix C Potential Flow Review</b>		<b>776</b>
<b>Appendix D Computational Aerodynamics Programs</b>		<b>790</b>
<b>Appendix E Structured Grid Transformations</b>		<b>802</b>
<b>Appendix F Commonly Used Turbulence Models</b>		<b>808</b>
	Glossary	823
	Index	833

*Color plates follow page 338*