

Contents

About the Authors	xi
Preface	xiii
Acknowledgments	xv
1 Characterization of Wireless Transmitter Distortions	1
1.1 Introduction	1
1.1.1 <i>RF Power Amplifier Nonlinearity</i>	2
1.1.2 <i>Inter-Modulation Distortion and Spectrum Regrowth</i>	2
1.2 Impact of Distortions on Transmitter Performances	6
1.3 Output Power versus Input Power Characteristic	9
1.4 AM/AM and AM/PM Characteristics	10
1.5 1 dB Compression Point	12
1.6 Third and Fifth Order Intercept Points	15
1.7 Carrier to Inter-Modulation Distortion Ratio	16
1.8 Adjacent Channel Leakage Ratio	18
1.9 Error Vector Magnitude	19
References	21
2 Dynamic Nonlinear Systems	23
2.1 Classification of Nonlinear Systems	23
2.1.1 <i>Memoryless Systems</i>	23
2.1.2 <i>Systems with Memory</i>	24
2.2 Memory in Microwave Power Amplification Systems	25
2.2.1 <i>Nonlinear Systems without Memory</i>	25
2.2.2 <i>Weakly Nonlinear and Quasi-Memoryless Systems</i>	26
2.2.3 <i>Nonlinear System with Memory</i>	27
2.3 Baseband and Low-Pass Equivalent Signals	27

2.4	Origins and Types of Memory Effects in Power Amplification Systems	29
2.4.1	<i>Origins of Memory Effects</i>	29
2.4.2	<i>Electrical Memory Effects</i>	30
2.4.3	<i>Thermal Memory Effects</i>	33
2.5	Volterra Series Models	38
	References	40
3	Model Performance Evaluation	43
3.1	Introduction	43
3.2	Behavioral Modeling versus Digital Predistortion	43
3.3	Time Domain Metrics	46
3.3.1	<i>Normalized Mean Square Error</i>	46
3.3.2	<i>Memory Effects Modeling Ratio</i>	47
3.4	Frequency Domain Metrics	48
3.4.1	<i>Frequency Domain Normalized Mean Square Error</i>	48
3.4.2	<i>Adjacent Channel Error Power Ratio</i>	49
3.4.3	<i>Weighted Error Spectrum Power Ratio</i>	50
3.4.4	<i>Normalized Absolute Mean Spectrum Error</i>	51
3.5	Static Nonlinearity Cancellation Techniques	52
3.5.1	<i>Static Nonlinearity Pre-Compensation Technique</i>	52
3.5.2	<i>Static Nonlinearity Post-Compensation Technique</i>	56
3.5.3	<i>Memory Effect Intensity</i>	59
3.6	Discussion and Conclusion	61
	References	62
4	Quasi-Memoryless Behavioral Models	63
4.1	Introduction	63
4.2	Modeling and Simulation of Memoryless/Quasi-Memoryless Nonlinear Systems	63
4.3	Bandpass to Baseband Equivalent Transformation	67
4.4	Look-Up Table Models	69
4.4.1	<i>Uniformly Indexed Look-Up Tables</i>	69
4.4.2	<i>Non-Uniformly Indexed Look-Up Tables</i>	70
4.5	Generic Nonlinear Amplifier Behavioral Model	71
4.6	Empirical Analytical Based Models	73
4.6.1	<i>Polar Saleh Model</i>	73
4.6.2	<i>Cartesian Saleh Model</i>	74
4.6.3	<i>Frequency-Dependent Saleh Model</i>	76
4.6.4	<i>Ghorbani Model</i>	76
4.6.5	<i>Berman and Mahle Phase Model</i>	77
4.6.6	<i>Thomas–Weidner–Durrani Amplitude Model</i>	77
4.6.7	<i>Limiter Model</i>	78
4.6.8	<i>ARCTAN Model</i>	79

4.6.9	<i>Rapp Model</i>	81
4.6.10	<i>White Model</i>	82
4.7	Power Series Models	82
4.7.1	<i>Polynomial Model</i>	82
4.7.2	<i>Bessel Function Based Model</i>	83
4.7.3	<i>Chebyshev Series Based Model</i>	84
4.7.4	<i>Gegenbauer Polynomials Based Model</i>	84
4.7.5	<i>Zernike Polynomials Based Model</i>	85
	References	86
5	Memory Polynomial Based Models	89
5.1	Introduction	89
5.2	Generic Memory Polynomial Model Formulation	90
5.3	Memory Polynomial Model	91
5.4	Variants of the Memory Polynomial Model	91
5.4.1	<i>Orthogonal Memory Polynomial Model</i>	91
5.4.2	<i>Sparse-Delay Memory Polynomial Model</i>	93
5.4.3	<i>Exponentially Shaped Memory Delay Profile Memory Polynomial Model</i>	95
5.4.4	<i>Non-Uniform Memory Polynomial Model</i>	96
5.4.5	<i>Unstructured Memory Polynomial Model</i>	97
5.5	Envelope Memory Polynomial Model	98
5.6	Generalized Memory Polynomial Model	101
5.7	Hybrid Memory Polynomial Model	106
5.8	Dynamic Deviation Reduction Volterra Model	108
5.9	Comparison and Discussion	111
	References	113
6	Box-Oriented Models	115
6.1	Introduction	115
6.2	Hammerstein and Wiener Models	115
6.2.1	<i>Wiener Model</i>	116
6.2.2	<i>Hammerstein Model</i>	117
6.3	Augmented Hammerstein and Wiener Models	118
6.3.1	<i>Augmented Wiener Model</i>	118
6.3.2	<i>Augmented Hammerstein Model</i>	119
6.4	Three-Box Wiener–Hammerstein Models	120
6.4.1	<i>Wiener–Hammerstein Model</i>	120
6.4.2	<i>Hammerstein–Wiener Model</i>	120
6.4.3	<i>Feedforward Hammerstein Model</i>	121
6.5	Two-Box Polynomial Models	123
6.5.1	<i>Models' Descriptions</i>	123
6.5.2	<i>Identification Procedure</i>	124

6.6	Three-Box Polynomial Models	124
6.6.1	<i>Parallel Three-Blocks Model: PLUME Model</i>	124
6.6.2	<i>Three Layered Biased Memory Polynomial Model</i>	125
6.6.3	<i>Rational Function Model for Amplifiers</i>	127
6.7	Polynomial Based Model with I/Q and DC Impairments	128
6.7.1	<i>Parallel Hammerstein (PH) Based Model for the Alleviation of Various Imperfections in Direct Conversion Transmitters</i>	129
6.7.2	<i>Two-Box Model with I/Q and DC Impairments</i>	129
	References	130
7	Neural Network Based Models	133
7.1	Introduction	133
7.2	Basics of Neural Networks	133
7.3	Neural Networks Architecture for Modeling of Complex Static Systems	137
7.3.1	<i>Single-Input Single-Output Feedforward Neural Network (SISO-FFNN)</i>	137
7.3.2	<i>Dual-Input Dual-Output Feedforward Neural Network (DIDO-FFNN)</i>	138
7.3.3	<i>Dual-Input Dual-Output Coupled Cartesian Based Neural Network (DIDO-CC-NN)</i>	139
7.4	Neural Networks Architecture for Modeling of Complex Dynamic Systems	140
7.4.1	<i>Complex Time-Delay Recurrent Neural Network (CTDRNN)</i>	141
7.4.2	<i>Complex Time-Delay Neural Network (CTDNN)</i>	142
7.4.3	<i>Real Valued Time-Delay Recurrent Neural Network (RVTDRNN)</i>	142
7.4.4	<i>Real Valued Time-Delay Neural Network (RVTDNN)</i>	144
7.5	Training Algorithms	147
7.6	Conclusion	150
	References	151
8	Characterization and Identification Techniques	153
8.1	Introduction	153
8.2	Test Signals for Power Amplifier and Transmitter Characterization	155
8.2.1	<i>Characterization Using Continuous Wave Signals</i>	155
8.2.2	<i>Characterization Using Two-Tone Signals</i>	156
8.2.3	<i>Characterization Using Multi-Tone Signals</i>	157
8.2.4	<i>Characterization Using Modulated Signals</i>	158
8.2.5	<i>Characterization Using Synthetic Modulated Signals</i>	160
8.2.6	<i>Discussion: Impact of Test Signal on the Measured AM/AM and AM/PM Characteristics</i>	160

8.3	Data De-Embedding in Modulated Signal Based Characterization	163
8.4	Identification Techniques	170
8.4.1	<i>Moving Average Techniques</i>	170
8.4.2	<i>Model Coefficient Extraction Techniques</i>	172
8.5	Robustness of System Identification Algorithms	179
8.5.1	<i>The LS Algorithm</i>	179
8.5.2	<i>The LMS Algorithm</i>	179
8.5.3	<i>The RLS Algorithm</i>	180
8.6	Conclusions	181
	References	181
9	Baseband Digital Predistortion	185
9.1	The Predistortion Concept	185
9.2	Adaptive Digital Predistortion	188
9.2.1	<i>Closed Loop Adaptive Digital Predistorters</i>	188
9.2.2	<i>Open Loop Adaptive Digital Predistorters</i>	189
9.3	The Predistorter's Power Range in Indirect Learning Architectures	191
9.3.1	<i>Constant Peak Power Technique</i>	193
9.3.2	<i>Constant Average Power Technique</i>	193
9.3.3	<i>Synergetic CFR and DPD Technique</i>	194
9.4	Small Signal Gain Normalization	194
9.5	Digital Predistortion Implementations	201
9.5.1	<i>Baseband Digital Predistortion</i>	201
9.5.2	<i>RF Digital Predistortion</i>	204
9.6	The Bandwidth and Power Scalable Digital Predistortion Technique	205
9.7	Summary	206
	References	207
10	Advanced Modeling and Digital Predistortion	209
10.1	Joint Quadrature Impairment and Nonlinear Distortion Compensation Using Multi-Input DPD	209
10.1.1	<i>Modeling of Quadrature Modulator Imperfections</i>	210
10.1.2	<i>Dual-Input Polynomial Model for Memoryless Joint Modeling of Quadrature Imbalance and PA Distortions</i>	211
10.1.3	<i>Dual-Input Memory Polynomial for Joint Modeling of Quadrature Imbalance and PA Distortions Including Memory Effects</i>	212
10.1.4	<i>Dual-Branch Parallel Hammerstein Model for Joint Modeling of Quadrature Imbalance and PA Distortions with Memory</i>	213
10.1.5	<i>Dual-Conjugate-Input Memory Polynomial for Joint Modeling of Quadrature Imbalance and PA Distortions Including Memory Effects</i>	216

10.2	Modeling and Linearization of Nonlinear MIMO Systems	216
10.2.1	<i>Impairments in MIMO Systems</i>	216
10.2.2	<i>Crossover Polynomial Model for MIMO Transmitters</i>	221
10.2.3	<i>Dual-Input Nonlinear Polynomial Model for MIMO Transmitters</i>	222
10.2.4	<i>MIMO Transmitters Nonlinear Multi-Variable Polynomial Model</i>	223
10.3	Modeling and Linearization of Dual-Band Transmitters	227
10.3.1	<i>Generalization of the Polynomial Model to the Dual-Band Case</i>	228
10.3.2	<i>Two-Dimensional (2-D) Memory Polynomial Model for Dual-Band Transmitters</i>	230
10.3.3	<i>Phase-Aligned Multi-band Volterra DPD</i>	231
10.4	Application of MIMO and Dual-Band Models in Digital Predistortion	235
10.4.1	<i>Linearization of MIMO Systems with Nonlinear Crosstalk</i>	236
10.4.2	<i>Linearization of Concurrent Dual-Band Transmitters Using a 2-D Memory Polynomial Model</i>	238
10.4.3	<i>Linearization of Concurrent Tri-Band Transmitters Using 3-D Phase-Aligned Volterra Model</i>	240
	References	242
	Index	247