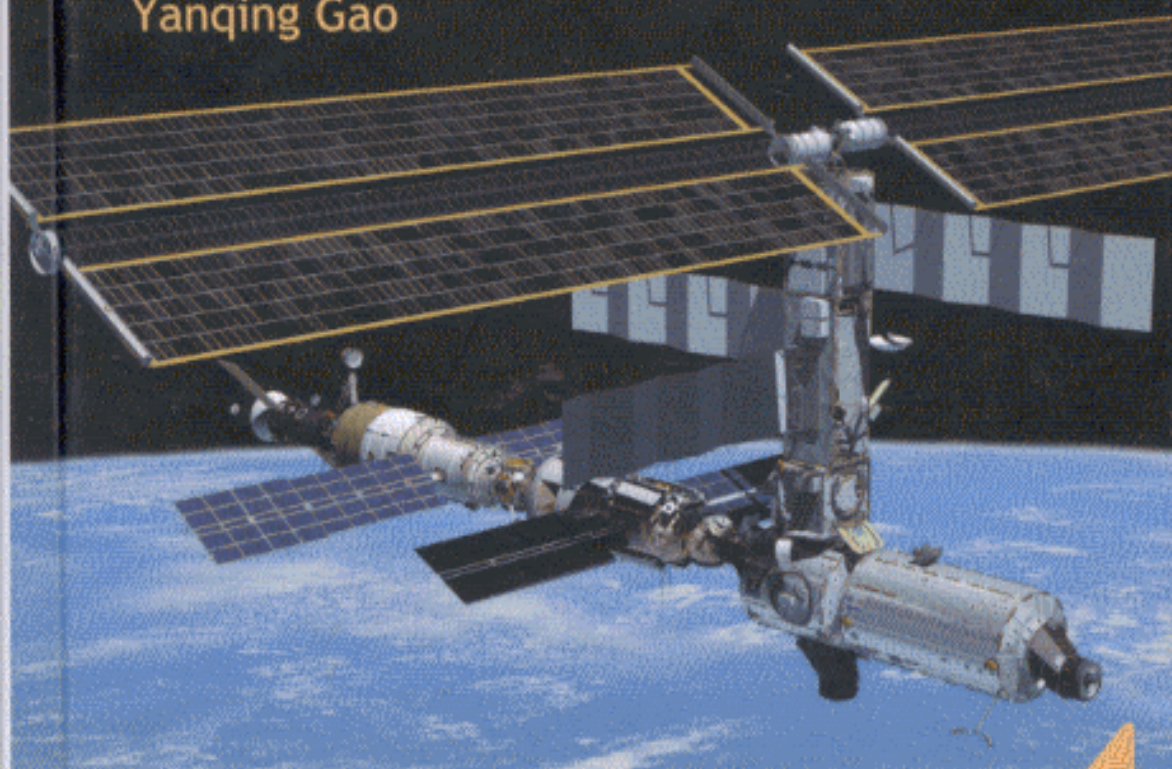


Advanced Studies of Flexible Robotic Manipulators

Modeling, Design, Control and Applications

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