

CONTENTS

Preface	χV
Introduction	xvi
Chapter 1 Project Management	1
Project Management	2
Project Process Flowchart	3
How This Works When It's Implemented Right	Ę
The User's Manual for the "Boss"	Ę
The User's Manual for PMs	6
Conclusion	17
Chapter 2 Control Systems	19
Distributed Control Systems	22
Central Control Systems	24
Open-Loop Control	24
Closed-Loop Control	26
Designing the Control System	39
Notes on Robot Design	50
Multivariable Control Systems	58
Time	67
Space	69
Chapter 3 Computer Hardware	73
Leverage Existing Technology	75
Speeding Up Engineering	77
Computer Architecture	77
Process for Choosing a Robot's Computer Hardware	113

Chapter 4 Reliability, Safety, and Compliance	123
Reliability	123
Safety	128
Environmental Considerations	132
Common Sense	135
Emissions	138
Quality Issues	143
Testing	144
Chapter 5 Design Steps: HLD	147
Power	147
Locomotion	148
Automation	148
Chapter 6 Energy and Power Systems	153
Energy	154
Energy Sources	157
Chapter 7 Energy Control and Software	159
Considerations	159
Energy Conservation	162
Hardware Considerations	164
Spy-hopping	176
Software Considerations for Energy Control	178
Mechanical Considerations: Software for Energy Control	183
Chapter 8 Digital Signal Processing (DSP)	191
The Nyquist-Shannon Sampling Theorem	192
A/D Conversion	198
A/D Dithering	200
Sample and Hold (S/H)	201
Antialias Filters	201
D/A Effects: Sinc Compensation	207
DSP Filter Design	208

	CONTENTS VII
Physical Implementation of DSP Filters	215
Multirate DSP	220
Chapter 9 Communications	221
OSI Seven-Layer Model	224
Physical Layer	226
Baseband Transmission	228
Modulated Communications	232
Error Control	238
Shared Access	258
Compression	265
Encryption and Security	266
Popular Communication Channels	269
Chapter 10 Motors and Actuators	275
AC Motors	275
DC Motors	276
Exotic Motors	279
Chapter 11 Mechanics	281
Materials	282
Some Cautions	285
Static Mechanics	287
Dynamic Mechanics	288
Index	293