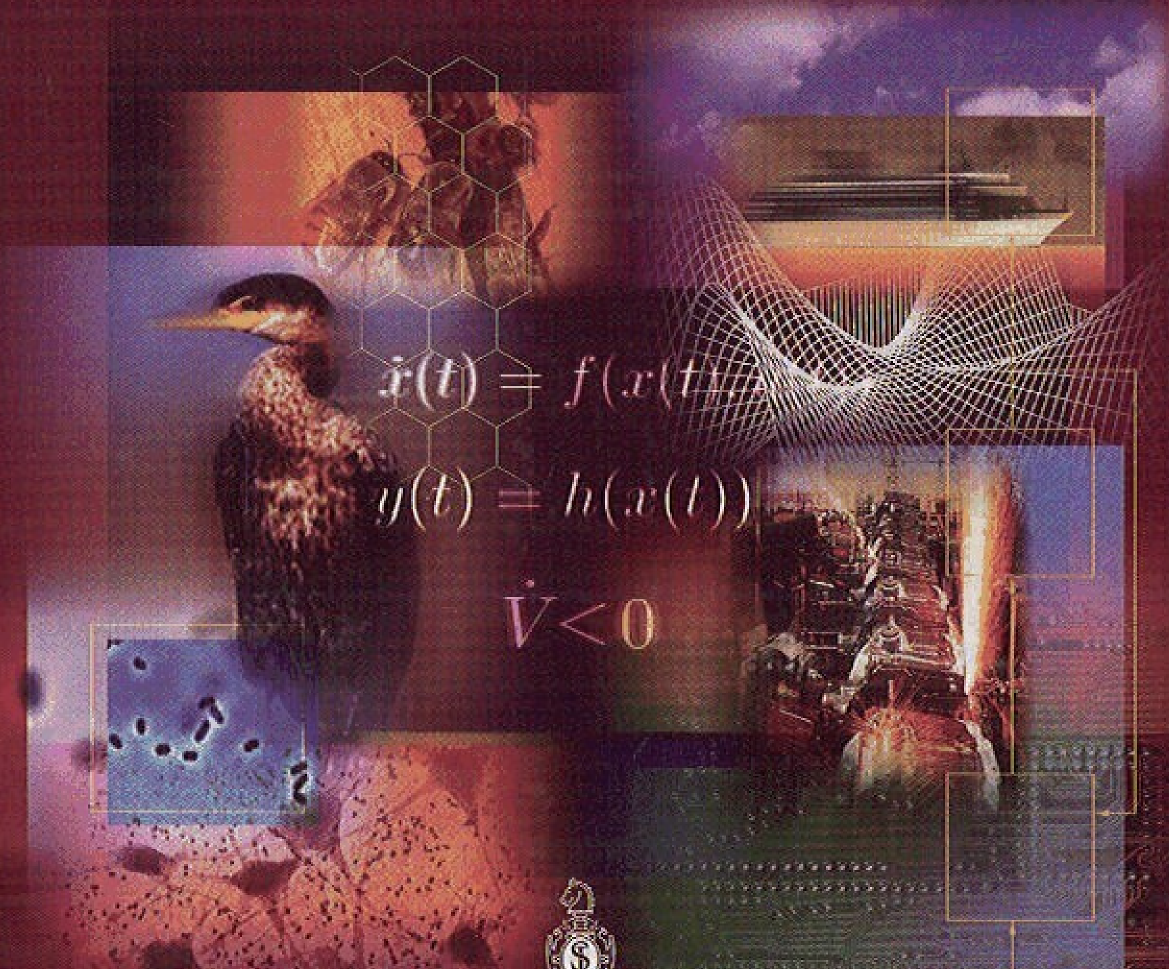
Kevin M. Passino

Biomimicry for Optimization, Control, and Automation



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